

SLDN-40E1A Non-Isolated DC-DC Converter

The SLDN-40E1A modules are non-isolated DC-DC converters that can deliver up to 40 A of output current. These modules operate over a wide range of input voltage (VIN = 4.5 - 14.4 VDC) and provide a precisely regulated output voltage from 0.45 VDC to 2.0 VDC, programmable via an external resistor and power management bus control.

Features include a digital interface using the power management bus protocol, remote on/off, adjustable output voltage, over current and over temperature protection. The power management bus interface supports a range of commands to both control and monitor the module. The module also includes the Tunable LoopTM feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.



Key Features & Benefits

- Non-Isolated
- Wide Input Voltage Range (4.5 14.4 VDC)
- Power Good Signal
- Remote On/Off
- Cost Efficient Open Frame Design
- Ability to Sink and Source Current
- Over Temperature Protection
- Output Voltage Programmable from 0.6 to 2.0 VDC via External Resistor Digitally Adjustable Down to 0.45 VDC
- Digital Interface Through the Power Management Bus Protocol
- Tunable Loop[™] to Optimize Dynamic Output Voltage Response
- Fixed Switching Frequency with Capability of External Synchronization
- Output Over-Current Protection (non-latching)
- Wide Operating Temperature Range [-40°C to 85°C]
- Approved to IEC/EN 62368-1
- Approved to UL/CSA 62368-1
- Class II, Category 2, Isolated DC/DC Converter (refer to IPC-9592B)
- Small size: $33.02 \times 13.46 \times 10.9 \text{ mm} (1.3 \times 0.53 \times 0.429 \text{ inch})$



RoHS Compliant

Applications

- Distributed Power Architectures
- Servers and Storage Applications
- Intermediate Bus Voltage Applications
- Networking Equipment
- Telecommunications Equipment
- Industrial Equipment



1. MODEL SELECTION

MODEL NUMBER ACTIVE LOW	MODEL NUMBER ACTIVE HIGH	OUTPUT VOLTAGE	INPUT VOLTAGE	MAX. OUTPUT CURRENT	MAX. OUTPUT POWER	TYPICAL EFFICIENCY 51VDC
SLDN-40E1ALG	SLDN-40E1A0G	0.45 - 2.0 VDC	4.5 – 14.4 VDC	40 A	80 W	91.5%
SLDN-40E1ALR	SLDN-40E1A0R	0.10 2.0 120	1.0 11.1100	1071	00 11	01.070

PART NUMBER EXPLANATION

S	LDN	40	E	1A	х	x
Mounting type	Series code	Output current	Input voltage range	Sequencing or not	Logic status	Package
Surface	SLDN series	40 A	4.5 - 14.4 V	With	0 – Active High	G - Tray Package
mount		.571		Sequencing	L – Active Low	R - Tape & Reel Package

2. ABSOLUTE MAXIMUM RATINGS

PARAMETER	DESCRIPTION	MIN	TYP	UNITS
Continuous Input Voltage		-0.3	15	V
Voltage on SEQ, SYNC, VS+		-	7	V
Voltage on CLK, DATA, SMBALERT Terminal		-	3.6	V
Operating Ambient Temperature	See Thermal Considerations section	-40	85	°C
Storage Temperature		-55	125	°C
Altitude		-	4000	m

NOTE: Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

3. INPUT SPECIFICATIONS

PARAMETER	DESCRIPTION		MIN	TYP	MAX	UNIT
Operating Input Voltage			4.5	-	14.4	٧
Input Current	VIN = 4.5 to 14 V, lo =	= lo max	-	-	24	Α
Input Current (no load)	Vo set = 0.6 VDC	VIN = 12 VDC, lo = 0,	-	54.7	-	mA
Input Current (no load)	Vo set = 2 VDC module enabled	-	104	-	IIIA	
Input Stand-by Current	VIN = 12 V, module d	isabled	-	12.5	-	mA
Input Reflected Ripple Current (pk-pk)		source impedance; VIN = ; See Test Configurations	-	90	-	mA
I ² t Inrush Current Transient			-	-	1	A^2s
Input Ripple Rejection (120 Hz)			-	-60	-	dB

NOTE: Unless otherwise indicated, specifications apply over entire operating input voltage range, resistive load, and temperature conditions.



4. OUTPUT SPECIFICATIONS

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Output Voltage Set Point		With 0.1% tolerance for external resistor used to set output voltage	-1.0	-	+1.0	%Vo set
Output Voltage		Over entire operating input voltage range, resistive load, and temperature conditions until end of life	-3.0	-	+3.0	%Vo set
Power Manager Adjustable Outp	nent bus out Voltage Range		-25	0	+25	%Vo set
Power Manager Voltage Adjustm	nent bus Output nent Step Size		0.4	-	-	%Vo set
Adjustment Ran	ge	Selected by an external resistor Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section	0.6	-	2.0	V
Remote Sense F	Range		-	-	0.5	V
Line Regulation		VIN = VIN min to VIN max	-	-	6	mV
Load Regulation	1	lo = lo min to lo max	-	-	10	mV
Temperature Re	gulation	Tref = Ta min to Ta max	-	0.4	-	%Vo set
Output Current		In either sink or source mode	0	-	40	Α
Output Ripple a	nd Noise (pk-pk)	5 Hz to 20 MHz BW, VIN = VIN nom and Io = Io min to	-	50	100	mV
Output Ripple a	nd Noise (rms)	Io max Co = 0.1 μ F // 22 μ F ceramic capacitors)	-	20	38	mV
Output Short-Ci	rcuit Current	Vo ≤ 250 mV, Hiccup Mode	-	2.1	2.83	Arms
Turn-On Delay 1	- Times	Case 1: On/Off input is enabled and then input power is applied (delay from instant at which VIN = VIN min until Vo = 10% of Vo set)	1.0	1.1	1.7	ms
(VIN=VIN nom, lo=lo max, Vo to within ±1% of steady state.)		Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until Vo = 10% of Vo set)	600	700	1800	μѕ
Output Voltage	Overshoot	VIN = VIN min to Vin max, Io = Io min to Io max, TA = 25°C. With or without maximum external capacitance	0	1.5	3.0	%Vo set.
Output Voltage	Rise Time	Time for Vo to rise from 10% of Vo set to 90% of Vo set	1.2	1.5	2.2	ms
Output	ESR ≥ 1 mΩ	Without the Tunable $Loop^TM$	6x47	-	6x47	
Capacitance**	ESR ≥ 0.15 mΩ	With the Tunable $Loop^TM$	6x47	-	7000	μF
	ESR ≥ 10 mΩ	With the Tunable $Loop^TM$	6x47	-	8500	
Output Current	Limit Inception	Current limit does not operate in sink mode	-	150	180	% lo max

^{**} External capacitors may require using the new Tunable LoopTM feature to ensure that the module is stable as well as getting the best transient response. See the Tunable LoopTM section for details.



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5. GENERAL SPECIFICATIONS

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
		Vo = 0.6 V	78.0	81.3	-	
Efficiency	Vin = 12 VDC, TA = 25°C lo = lo max, Vo = Vo set	Vo = 1.2 V	84.0	88.5	-	%
	10 - 10 max, vo - vo set	Vo = 1.8 V	85.25	91.5	-	
Switching Frequency			380	400	420	kHz
Synchronization Frequency Range			350	-	480	kHz
High-Level Input Voltage			2.0	-	-	V
Low-Level Input Voltage			-	-	0.4	V
Input Current, SYNC			-	-	100	nA
Minimum Pulse Width, SYNC			100	-	-	ns
Maximum SYNC Rise Time			100	-	-	ns
Over Temperature Protection			123	130	137	°C
Power Management Bus Over Temperature Warning Threshold	Warning may not activate before alarm and shutdown before warning.	d unit may	120	130	140	°C
Power Management Bus Adjustable Input Under Voltage Lockout Thresholds			2.5	-	14	V
Resolution of Adjustable Input Under Voltage Threshold			-	-	500	mV
Tracking Accuracy	Power-Up: 0.5 V/ms	Vin, min to Vin, max; Io, min to Io, max,	-	-	100	mV
Tracking Accuracy	Power-Down: 0.5 V/ms	V _{SEQ} < V _o	-	-	100	1110
	Overvoltage threshold for PGOOD ON		103	108	113	%Vo set
	Overvoltage threshold for PGOOD OFF		105	110	115	%Vo set
PGOOD (Power Good)	Undervoltage threshold for PGOOD ON	Signal Interface Open Drain,	87	92	97	%Vo set
rdood (rower dood)	Undervoltage threshold for PGOOD OFF	Vsupply ≤ 5 VDC	85	90	95	%Vo set
	Pulldown resistance of PGOOD pin		-	-	50	Ω
	Sink current capability into PGOOD pin		-	-	5	mA
Weight			10.53	11.7	12.87	g
	Turn-on Threshold		4.144	4.25	4.407	
Input Undervoltage Lockout	Turn-off Threshold		3.947	3.98	4.163	V
			0.25	0.3	0.35	
	Hysteresis		0.25	0.5	0.00	
MTBF	Hysteresis Calculated MTBF (Io = 0.8 Io max, TA = 40 Telecordia Issue 2 Method 1 Case 3	o°C)	0.23	6,498,438		hours
MTBF Dimensions (L × W × H)	Calculated MTBF (Io = 0.8 Io max, TA = 40)°C)				hours

NOTE: Unless otherwise indicated, specifications apply over entire operating input voltage range, resistive load, and temperature condition.



6. DIGITAL INTERFACE SPECIFICATIONS

Power Management Bus Signal Interface Characteristics	PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Input Low Voltage (CLK, DATA)	Power Management Bus Signal Interfac	ce Characteristics				
Input High Level Current (CLK, DATA) -10 - 10 μA Input Low Level Current (CLK, DATA) -10 - 10 μA Output Low Voltage (CLK, DATA) lout = 2 mA - - 0.4 V CULD LT High Level Open Drain Leakage Current (DATA, SMBALERT#) Vout = 3.6 V 0 - 10 μA Pin Capacitance - 0.7 - pF Power Management Bus Operating Frequency Range 10 - 400 kHz Pata Setup Time 250 - - ns Data Hold Time Receive Mode 0 - - ns Measurement System Characteristics Transmit Mode 300 - - ns Measurement System Characteristics Transmit Measurement Resolution 62.5 - - mA Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - - - - - - - -	Input High Voltage (CLK, DATA)		2.1	-	3.6	٧
Input Low Level Current (CLK, DATA)	Input Low Voltage (CLK, DATA)		-	-	0.8	V
Output Low Voltage (CLK, DATA, SMBALERT#) lout = 2 mA - - 0.4 V Output High Level Open Drain Leakage Current (DATA, SMBALERT#) Vout = 3.6 V 0 - 10 µA Pin Capacitance - 0.7 - pF Power Management Bus Operating Frequency Range 10 - 400 kHz Power Management Bus Operating Frequency Range 250 - - ns Data Setup Time 250 - - ns Data Hold Time Receive Mode Transmit Mode 0 - - ns Measurement System Characteristics Measurement System Characteristics Name Accuracteristics Measurement Read Delay Time 153 192 231 µs Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Offset 62.5 - - mA Vour Measurement Resolution - 16.25 - mV Vour Measurement Gain Acc	Input High Level Current (CLK, DATA)		-10	-	10	μΑ
CLIK, DATA, SMEALERT#) Iolit = 2 mA	Input Low Level Current (CLK, DATA)		-10	-	10	μΑ
Current (DATA, SMBALERT#) Volut = 3.6 V 0 - 10 pA Pin Capacitance - 0.7 - pF Power Management Bus Operating Frequency Range 10 - 400 kHz Data Setup Time 250 - - ns Data Hold Time Receive Mode Transmit Mode 0 - - ns Measurement System Characteristics Transmit Mode 300 - - ns Measurement System Characteristics - - - ns - ns Measurement System Characteristics - - - ns - - - ns - - - - ns - - - - - - - - - - - - - - - - - - -	(CLK, DATA, SMBALERT#)	lout = 2 mA	-	-	0.4	V
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Frequency Range 10 - 400 RR2 Data Setup Time 250 - - ns Data Hold Time Receive Mode 0 - - ns Measurement System Characteristics Read Delay Time 153 192 231 μs Output Current Measurement Range 0 - 40 A Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - - - MA Vour Measurement Range 0 -<			-	0.7	-	pF
Data Hold Time Receive Mode Transmit Mode 0 - - ns Measurement System Characteristics Read Delay Time 153 192 231 μs Output Current Measurement Range 0 - 40 A Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - - % Output Current Measurement Range 0 - 2.0 V Vour Measurement Range 0 - 2.0 V Vour Measurement Range 0 - 2.0 V Vour Measurement Gain Accuracy -2 - 2 LSB Vour Measurement Accuracy -15 - 15 % Vour Measurement Range 0 - 15 % Vour Measurement Range - 15 - 15 % Vour Measurement Range 0 - 14.4 V Vin Measurement Range 0<			10	-	400	kHz
Data Hold Time Transmit Mode 300 - - ns Measurement System Characteristics Read Delay Time 153 192 231 µs Output Current Measurement Range 0 - 40 A Output Current Measurement Gain Accuracy - - - mA Output Current Measurement Offset - - - - Measurement Range 0 - - - - Output Current Measurement Range 0 - - - - - Measurement Range 0 -	Data Setup Time		250	-	-	ns
Measurement System Characteristics Measurement System Characteristics Read Delay Time 153 192 231 µs Output Current Measurement Range 0 - 40 A Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - 0.1 A Vour Measurement Range 0 - 2.0 V Vour Measurement Resolution - 16.25 - mV Vour Measurement Gain Accuracy -2 - 2 LSB Vour Measurement Accuracy -15 - 15 % Vour Measurement Range 0 - 14.4 V Vo Measurement Range 0 - 14.4 V Vin Measurement Range 0 - 14.4 V Vin Measurement Range - 32.5 - mV Vin Measurement Gain Accuracy - 2 - 2 LSB Vin Measurement Gain Accuracy	Data Hold Time	Receive Mode	0	-	-	ns
Read Delay Time 153 192 231 µs Output Current Measurement Range 0 - 40 A Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - 5 % Output Current Measurement Offset - - 0.1 A Vour Measurement Range 0 - 2.0 V Vour Measurement Resolution - 16.25 - mV Vour Measurement Gain Accuracy -2 - 2 LSB Vour Measurement Accuracy -15 - 15 % Vin Measurement Range 0 - 14.4 V Vin Measurement Resolution - 32.5 - mV Vin Measurement Gain Accuracy -2 - 2 LSB Vin Measurement Gain Accuracy -2 - 2 LSB Vin Measurement Offset -5.5 - 1.4 %	Data Florid Filline	Transmit Mode	300	-	-	ns
Output Current Measurement Range 0 - 40 A Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - ±5 % Output Current Measurement Offset - - 0.1 A Vout Measurement Range 0 - 2.0 V Vout Measurement Resolution - 16.25 - mV Vout Measurement Gain Accuracy -2 - 2 LSB Vout Measurement Accuracy -15 - 15 % Vin Measurement Range 0 - 14.4 V Vin Measurement Resolution - 32.5 - mV Vin Measurement Gain Accuracy - 2 - 2 LSB Vin Measurement Gain Accuracy - 2 - 2 LSB Vin Measurement Offset - - 1.4 %	Measurement System Characteristics					
Output Current Measurement Resolution 62.5 - - mA Output Current Measurement Gain Accuracy - - ±5 % Output Current Measurement Offset - - 0.1 A Vout Measurement Range 0 - 2.0 V Vout Measurement Resolution - 16.25 - mV Vout Measurement Gain Accuracy -2 - 2 LSB Vout Measurement Offset -3 - 3 % Vout Measurement Range 0 - 15 % Vin Measurement Range 0 - 14.4 V Vin Measurement Resolution - 32.5 - mV Vin Measurement Gain Accuracy -2 - 2 LSB Vin Measurement Gain Accuracy -2 - 2 LSB	Read Delay Time		153	192	231	μs
Output Current Measurement Gain Accuracy - - ±5 % Output Current Measurement Offset - - - 0.1 A Vout Measurement Range 0 - 2.0 V Vout Measurement Resolution - 16.25 - mV Vout Measurement Gain Accuracy -2 - 2 LSB Vout Measurement Accuracy -15 - 15 % Vin Measurement Range 0 - 14.4 V Vin Measurement Resolution - 32.5 - mV Vin Measurement Gain Accuracy - 2 - 2 LSB Vin Measurement Gain Accuracy - 2 - 2 LSB Vin Measurement Offset - - 1.4 %	Output Current Measurement Range		0	-	40	Α
Accuracy -<	•		62.5	-		
Vour Measurement Range 0 - 2.0 V Vour Measurement Resolution - 16.25 - mV Vour Measurement Gain Accuracy -2 - 2 LSB Vour Measurement Offset -3 - 3 % Vour Measurement Accuracy -15 - 15 % Vin Measurement Range 0 - 14.4 V Vin Measurement Resolution - 32.5 - mV Vin Measurement Gain Accuracy -2 - 2 LSB Vin Measurement Offset -5.5 - 1.4 %			-	-	±5	%
Vour Measurement Resolution - 16.25 - mV Vour Measurement Gain Accuracy -2 - 2 LSB Vour Measurement Offset -3 - 3 % Vour Measurement Accuracy -15 - 15 % V _{IN} Measurement Range 0 - 14.4 V V _{IN} Measurement Resolution - 32.5 - mV V _{IN} Measurement Gain Accuracy -2 - 2 LSB V _{IN} Measurement Offset -5.5 - 1.4 %	Output Current Measurement Offset		-	-	0.1	Α
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Vour Measurement Accuracy -15 - 15 % V _{IN} Measurement Range 0 - 14.4 V V _{IN} Measurement Resolution - 32.5 - mV V _{IN} Measurement Gain Accuracy -2 - 2 LSB V _{IN} Measurement Offset -5.5 - 1.4 %	Vout Measurement Gain Accuracy		-2	-	2	LSB
V _{IN} Measurement Range 0 - 14.4 V V _{IN} Measurement Resolution - 32.5 - mV V _{IN} Measurement Gain Accuracy -2 - 2 LSB V _{IN} Measurement Offset -5.5 - 1.4 %	Vout Measurement Offset		-3	-	3	%
V _{IN} Measurement Resolution - 32.5 - mV V _{IN} Measurement Gain Accuracy -2 - 2 LSB V _{IN} Measurement Offset -5.5 - 1.4 %	Vout Measurement Accuracy		-15	-	15	%
V _{IN} Measurement Gain Accuracy -2 - 2 LSB V _{IN} Measurement Offset -5.5 - 1.4 %	V _{IN} Measurement Range		0	-	14.4	V
V _{IN} Measurement Offset -5.5 - 1.4 %	V _{IN} Measurement Resolution		-	32.5	-	mV
	V _{IN} Measurement Gain Accuracy		-2	-	2	LSB
V _{IN} Measurement Accuracy - ±3 - %	V _{IN} Measurement Offset		-5.5	-	1.4	%
	V _{IN} Measurement Accuracy		-	±3	-	%

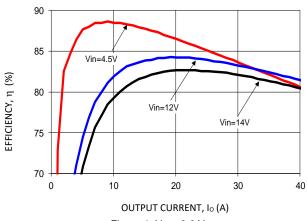
NOTE: Unless otherwise indicated, specifications apply over entire operating input voltage range, resistive load, and temperature condition.



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7. EFFICIENCY DATA



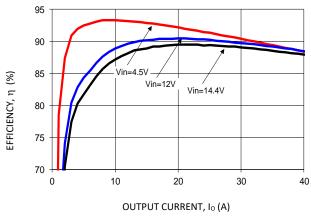


Figure 1. Vo = 0.6 V

Figure 2. Vo = 1.2 V

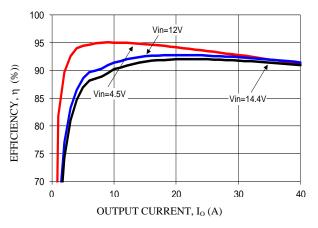
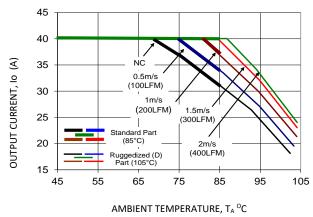


Figure 3. Vo = 1.8 V



8. THERMAL DERATING CURVES



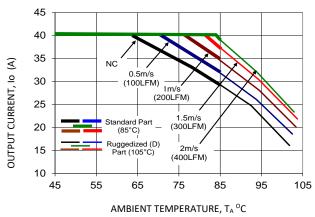


Figure 4. Vo = 0.6 V

Figure 5. Vo = 1.2 V

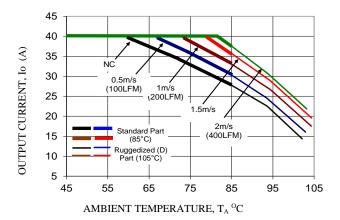


Figure 6. Vo = 1.8 V



9. OUTPUT RIPPLE AND NOISE WAVEFORMS

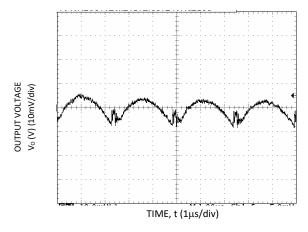


Figure 7. Vo = 0.6 V, Io = Io, max

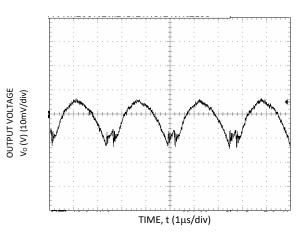


Figure 8. Vo = 1.2 V, Io = Io, max

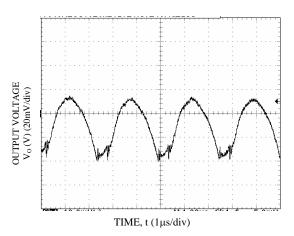


Figure 9. Vo = 1.8 V, Io = Io, max

NOTE: Co = $6x 47 \mu F$ ceramic, VIN = 12V, Io = Io,max.



10. STARTUP TIME

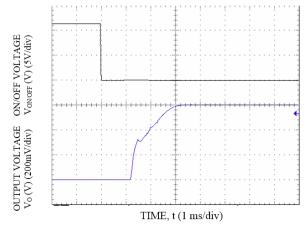


Figure 10. Start-up Using On/Off Voltage (Io = Io max), Vo = 0.6 V

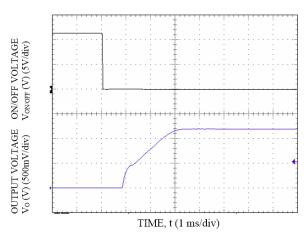


Figure 11. Start-up Using On/Off Voltage (Io = Io max), Vo = 1.2 V

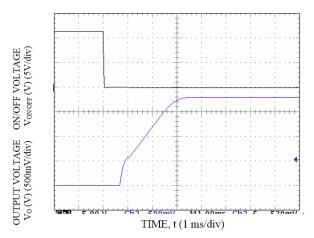


Figure 12. Start-up Using On/Off Voltage (Io = Io max), Vo = 1.8 V

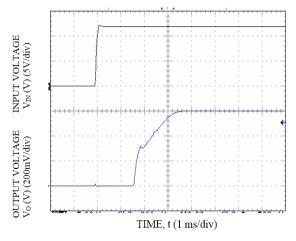


Figure 13. Start-up Using Input Voltage (VIN = 12 V, Io = Io max), Vo = 0.6 V

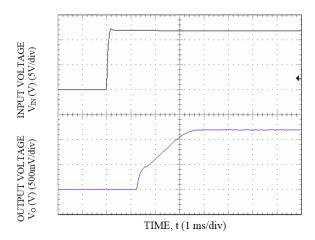


Figure 14. Start-up Using Input Voltage (VIN = 12 V, Io = Io max), Vo = 1.2 V

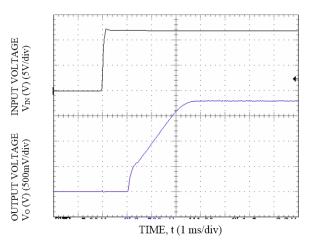


Figure 15. Start-up Using Input Voltage (VIN = 12 V, Io = Io max), Vo = 1.8 V



11. TRANSIENT RESPONSE WAVEFORMS

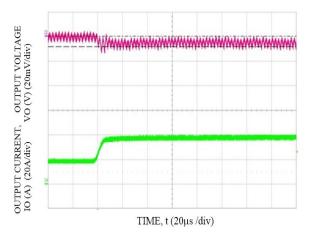


Figure 16. Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout = 12x 680 µF + 6x 47 µF, CTune = 47 nF, RTune = 180 ohms, Vo = 0.6 V

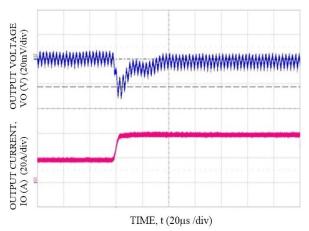


Figure 17. Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout = 6x 330 μF,

CTune = 12 nF & RTune = 200 ohms, Vo = 1.2 V

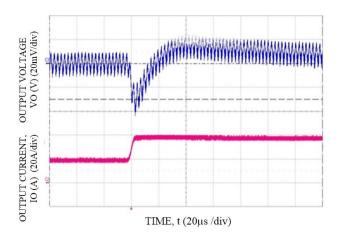


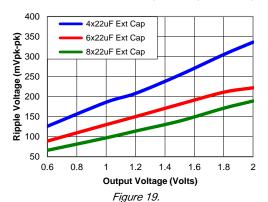
Figure 18. Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout = 6x 330 μF, CTune = 5.6 nF & RTune = 220 ohms, Vo = 1.8 V

12. DESIGN CONSIDERATIONS

INPUT FILTERING

The SLDN-40E1Ax module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 19 shows the input ripple voltage for various output voltages at 40 A of load current with 4x22 µF, 6x22 µF or 8x22 µF ceramic capacitors & an input of 12V.



NOTE: Input ripple voltage for various output voltages with various external ceramic capacitors at the input (40 A load). Input voltage is 12 V. Scope Bandwidth limited to 20 MHz.

OUTPUT FILTERING

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with $0.1~\mu F$ ceramic and $47~\mu F$ ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for several reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 20 provides output ripple information for different external capacitance values at various Vo and a full load current of 40 A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable LoopTM feature described later in this data sheet.

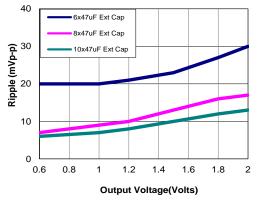


Figure 20.

NOTE: Output ripple voltage for various output voltages with external 6x47 μF, 8x47 μF or 10x47 μF ceramic capacitors at the output (40 A load). Input voltage is 12 V. Scope Bandwidth limited to 20 MHz.



13. SAFETY CONSIDERATIONS

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL/CSA 62368-1, IEC/EN 62368-1.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a fast-acting fuse with a maximum rating of 30 A, 100 V (for example, Bel Fuse SMM series) in the positive input lead.

14. ANALOG FEATURE DESCRIPTIONS

REMOTE ON/OFF

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Signal Low (Unit On)	Active Low	The remote on/off pin open Unit on	-0.2	-	0.4	
Signal High (Unit Off)	Active Low	The remote on/off pin open, Unit on.	2	-	VIN, max	V
Signal Low (Unit Off)	Active High	The remote on/off pin open, Unit on.	-0.3	-	0.4	V
Signal High (Unit On)	Active High		3.5	-	VIN, max	V

The SLDN-40E1Ax module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the Power management bus interface (Digital). The module can be configured in a number of ways through the Power management bus interface to react to the two ON/OFF inputs:

- · Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- · Module ON/OFF can be controlled only through the Power management bus interface (analog interface is ignored)
- · Module ON/OFF can be controlled by either the analog or digital interface.

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the Power management bus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

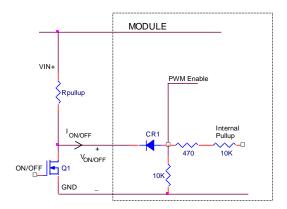
ANALOG ON/OFF

The SLDN-40E1Ax modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "0" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (device code suffix "L" – see Ordering Information n), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 21. For negative logic On/Off modules, the circuit configuration is shown in Figure 22.



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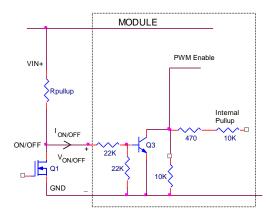


Figure 21. Circuit configuration for using positive On/Off logic

Figure 22. Circuit configuration for using negative On/Off logic

DIGITAL ON/OFF

Please see the Digital Feature Descriptions section.

MONOTONIC START-UP AND SHUTDOWN

The SLDN-40E1Ax module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

STARTUP INTO PRE-BIASED OUTPUT

The SLDN-40E1Ax module can start into a pre-biased output as long as the pre-bias voltage is 0.5 V less than the set output voltage.

ANALOG OUTPUT VOLTAGE PROGRAMMING

The output voltage of the module is programmable to any voltage from 0.6 Vdc to 2.0 Vdc by connecting a resistor between the Trim and SIG_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 23. The Upper Limit curve shows that for output voltages lower than 1 V, the input voltage must be lower than the maximum of 14.4 VDC. The Lower Limit curve shows that for output voltages higher than 0.6 V, the input voltage needs to be larger than the minimum of 4.5 VDC.

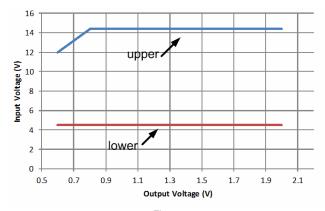


Figure 23.



NOTE: Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.

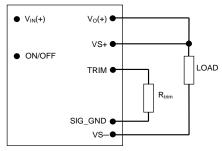


Figure 24.

CAUTION: Do not connect SIG_GND to GND elsewhere in the layout. Circuit configuration for programming output voltage using an external resistor.

Without an external resistor between Trim and SIG_GND pins, the output of the module will be 0.6 VDC. To calculate the value of the trim resistor, Rtrim for a desired output voltage, should be as per the following equation:

$$Rtrim = \left[\frac{12}{(Vo - 0.6)} \right] k\Omega$$

Rtrim is the external resistor in $k\Omega$. Vo is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

Rtrim (kΩ)
Open
40
30
20
13.33
10

Table 1.

DIGITAL OUTPUT VOLTAGE ADJUSTMENT

Please see the Digital Feature Descriptions section.

REMOTE SENSE

The SLDN-40E1Ax power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drops between the sense pins and the VOUT and GND pins of the module should not exceed 0.5 V.



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ANALOG VOLTAGE MARGINING

Output voltage margining can be implemented in the module by connecting a resistor, Rmargin-up, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, Rmargin-down, from the Trim pin to output pin for margining-down. Figure 25 shows the circuit configuration for output voltage margining. Please consult your local Bel representative for additional details.

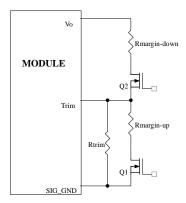


Figure 25. Circuit Configuration for margining Output voltage

DIGITAL OUTPUT VOLTAGE MARGINING

Please see the Digital Feature Descriptions section.

OUTPUT VOLTAGE SEQUENCING

The SLDN-40E1Ax module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig. 26. In addition, a small capacitor (suggested value 100 pF) should be connected across the lower resistor R1.

For SLDN-40E1Ax modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

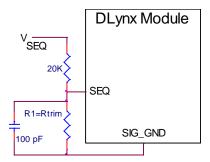


Figure 26. Circuit showing connection of the sequencing signal to the SEQ pin



When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5 V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set-point voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Note that in all digital Bel series of modules, the Power management bus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS_WORD and STATUS_VOUT Power management bus commands. In addition, the SMBALERT signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the power management bus command VOUT_UV_FAULT_RESPONSE for additional information).

OVER CURRENT PROTECTION

To provide protection in a fault (output overload) condition, the unit is equipped with internal current limiting circuitry and can endure current limiting continuously. At the point of current limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

LOAD TRANSIENT CONSIDERATIONS

The SLDN-40E1Ax module can achieve 100% load transient above 0 °C ambient temperature, the load transient is limited to a maximum of 62.5% of specified full load current.

DIGITAL ADJUSTABLE OVER CURRENT WARNING

Please see the Digital Feature Descriptions section.

OVER TEMPERATURE PROTECTION

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 145 °C (typ) is exceeded at the thermal reference point Tref. Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

DIGITAL TEMPERATURE STATUS VIA POWER MANAGEMENT BUS

Please see the Digital Feature Descriptions section.

DIGITALLY ADJUSTABLE OUTPUT OVER AND UNDER VOLTAGE PROTECTION

Please see the Digital Feature Descriptions section.

INPUT UNDERVOLTAGE LOCKOUT

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.



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DIGITALLY ADJUSTABLE INPUT UNDERVOLTAGE LOCKOUT

Please see the Digital Feature Descriptions section.

DIGITALLY ADJUSTABLE POWER GOOD THRESHOLDS

Please see the Digital Feature Descriptions section.

SYNCHRONIZATION

The SLDN-40E1Ax module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 27, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.

If synchronization is not being used, connect the SYNC pin to GND.

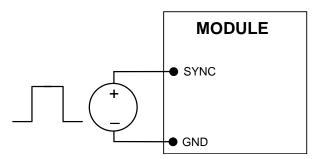


Figure 27. External source connections to synchronize switching frequency of the module

PARALLELING WITH ACTIVE LOAD SHARING

For additional power requirements, the Bel power module is also equipped with paralleling capability. Up to five modules can be configured in parallel, with active load sharing.

To implement paralleling, the following conditions must be satisfied.

- · All modules connected in parallel must be frequency synchronized where they are switching at the same frequency. This is done by using the SYNC function of the module and connecting to an external frequency source. Modules can be interleaved to reduce input ripple/filtering requirements.
- \cdot The share pins of all units in parallel must be connected together. The path of these connections should be as direct as possible.
- · The remote sense connections to all modules should be made that to same points for the output, i.e. all VS+ and VS- terminals for all modules are connected to the power bus at the same points.
- \cdot For converters operating in parallel, tunable loop components "RTUNE" and "CTUNE" must be selected to meet the required transient specification. For providing better noise immunity, we recommend that RTUNE value to be greater than 300 Ω .

Some special considerations apply for design of converters in parallel operation:

· When sizing the number of modules required for parallel operation, take note of the fact that current sharing has some tolerance. In addition, under transient conditions such as a dynamic load change and during startup, all converter output currents will not be equal. To allow for such variation and avoid the likelihood of a converter shutting off due to a current overload, the total capacity of the paralleled system should be no more than 90% of the sum of the individual converters. As an example, for a system of three converters in parallel, the total current drawn should be less than 90% of (3 x 40 A), i.e. less than 108 A.



All modules should be turned ON and OFF together. This is so that all modules come up at the same time avoiding the problem of one converter sourcing current into the other leading to an overcurrent trip condition. To ensure that all modules come up simultaneously, the on/off pins of all paralleled converters should be tied together and the converters enabled and disabled using the on/off pin. Note that this means that converters in parallel cannot be digitally turned ON as that does not ensure that all modules being paralleled turn on at the same time.

- · If digital trimming is used to adjust the overall output voltage, the adjustments need to be made in a series of small steps to avoid shutting down the output. Each step should be no more than 20 mV for each module. For example, to adjust the overall output voltage in a setup with two modules (A and B) in parallel from 1 V to 1.1 V, module A would be adjusted from 1.0 to 1.02 V followed by module B from 1.0 to 1.02 V, then each module in sequence from 1.02 to 1.04 V and so on until the final output voltage of 1.1 V is reached.
- · If the Sequencing function is being used to start-up and shut down modules and the module is being held to 0 V by the tracking signal then there may be small deviations on the module output. This is due to controller duty cycle limitations encountered in trying to hold the voltage down near 0 V.
- · The share bus is not designed for redundant operation and the system will be non-functional upon failure of one of the units when multiple units are in parallel. In particular, if one of the converters shuts down during operation, the other converters may also shut down due to their outputs hitting current limit. In such a situation, unless a coordinated restart is ensured, the system may never properly restart since different converters will try to restart at different times causing an overload condition and subsequent shutdown. This situation can be avoided by having an external output voltage monitor circuit that detects a shutdown condition and forces all converters to shut down and restart together.

When not using the active load share feature, share pins should be left unconnected.

MEASURING OUTPUT CURRENT, OUTPUT VOLTAGE AND INPUT VOLTAGE

Please see the Digital Feature Descriptions section.

DUAL LAYOUT

Identical dimensions and pin layout of Analog and Digital modules permit migration from one to the other without needing to change the layout. In both cases the trim resistor is connected between trim and signal ground.



TUNABLE LOOP™

The SLDN-40E1Ax module has a feature that optimizes transient response of the module called Tunable Loop™.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 20) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop[™] allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop[™] is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 28. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

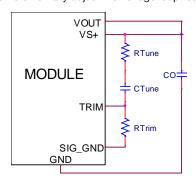


Figure 28. Circuit diagram showing connection of R_{TUNE} and C_{TUNE} to tune the control loop of the module

Recommended values of R_{TUNE} and C_{TUNE} for different output capacitor combinations are given in Table 2. Table 2 shows the recommended values of R_{TUNE} and C_{TUNE} for different values of ceramic output capacitors up to 1000 uF that might be needed for an application to meet output ripple and noise requirements. Selecting R_{TUNE} and C_{TUNE} according to Table 2 will ensure stable operation of the module.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} and C_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 20 A to 40 A step change (50% of full load), with an input voltage of 12 V.

Please contact your Bel representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

Со	6x 47 μF	8x 47 μF	10x 47 μF	12x 47 μF	20x 47 μF
RTUNE	330 Ω	330 Ω	330 Ω	330 Ω	200 Ω
CTUNE	330 pF	820 pF	1200 pF	1500 pF	3300 pF

Table 2.

General recommended values of of R_{TUNE} and C_{TUNE} for Vin = 12 V and various external ceramic capacitor combinations.

Vo	1.8 V	1.2 V	0.6 V
Co	4x 47 μF + 6x 330 μF polymer	4x 47 μF + 11x 330 μF polymer	4x 47 μF + 12x 680 μF polymer
RTUNE	220 Ω	200 Ω	180 Ω
CTUNE	5600 pF	12 nF	47 nF
ΔV	34 mV	22 mV	12 mV

Table 3.

Recommended values of R_{TUNE} and C_{TUNE} to obtain transient deviation of 2% of Vout for a 20 A step load with Vin = 12 V.

NOTE: The capacitors used in the Tunable Loop tables are 47 μ F/3 m Ω ESR ceramic, 330 μ F/12 m Ω ESR polymer capacitor and 680 μ F/12 m Ω polymer capacitor.



15. DIGITAL FEATURE DESCRIPTIONS

POWER MANAGEMENT BUS INTERFACE CAPABILITY

The SLDN-40E1Ax modules have a power management bus interface that supports both communication and control. The power management bus Power Management Protocol Specification can be obtained from www.power management bus.org. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using Power management bus and stored as defaults for later use.

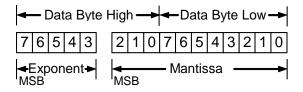
All communication over the module power management bus interface must support the Packet Error Checking (PEC) scheme. The Power management bus master must generate the correct PEC byte for all transactions and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

POWER MANAGEMENT BUS DATA FORMAT

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by Power management bus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by Value = Mantissa $x \ 2^{Exponent}$

POWER MANAGEMENT BUS ADDRESSING

The SLDN-40E1Ax module can be addressed through the Power management bus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.



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DIGIT	RESISTOR VALUE (ΚΩ)
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

Table 4.

The user must know which I2C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the Power management bus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

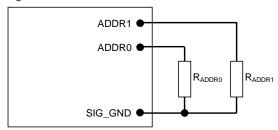


Figure 29.

Circuit showing connection of resistors used to set the Power management bus address of the module.

POWER MANAGEMENT BUS ENABLED ON/OFF

The module can also be turned on and off via the Power management bus interface. The OPERATION command is used to actually turn the module on and off via the Power management bus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and Power management bus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

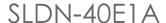
0 : Output is disabled1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows.

BIT POSITION	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the Power management bus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.





BIT VALUE	ACTION
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

BIT VALUE	ACTION
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

BIT VALUE	ACTION
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the POWER MANAGEMENT BUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

POWER MANAGEMENT BUS ADJUSTABLE SOFT START RISE TIME

The soft start rise time can be adjusted in the module via Power management bus. When setting this parameter, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON_RISE command sets the rise time in ms and allows choosing soft start times between 600 µs and 9 ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.

RISE TIME	EXPONENT	MANTISSA
600 μs	11100	00000001010
900 μs	11100	0000001110
1.2 ms	11100	00000010011
1.8 ms	11100	00000011101
2.7 ms	11100	00000101011
4.2 ms	11100	00001000011
6.0ms	11100	00001100000
9.0 ms	11100	00010010000

Table 5.



OUTPUT VOLTAGE ADJUSTMENT USING THE POWER MANAGEMENT BUS

The VOUT_SCALE_LOOP parameter is important for a number of Power management bus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is set as the combination of the voltage divider formed by RTrim and a $20k\Omega$ upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage VREF is nominally set at 600mV, and the output regulation voltage is then given by

$$V_{OUT} = \left\lceil \frac{20000 + RTrim}{RTrim} \right\rceil \times V_{REF}$$

Hence the module output voltage is dependent on the value of RTrim which is connected external to the module. The information on the output voltage divider ratio is conveyed to the module through the VOUT_SCALE_LOOP parameter which is calculated as follows:

$$VOUT_SCALE_LOOP = \frac{RTrim}{20000 + RTrim}$$

The VOUT_SCALE_LOOP parameter is specified using the "Linear" format and two bytes. The upper five bits [7:3] of the high byte are used to set the exponent which is fixed at -9 (decimal). The remaining three bits of the high byte [2:0] and the eight bits of the lower byte are used for the mantissa. The default value of the mantissa is 00100000000 corresponding to 256 (decimal), corresponding to a divider ratio of 0.5. The maximum value of the mantissa is 512 corresponding to a divider ratio of 1. Note that the resolution of the VOUT_SCALE_LOOP command is 0.2%.

When Power management bus commands are used to trim or margin the output voltage, the value of VREF is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module can be adjusted with a minimum step size of 0.4% over a $\pm 25\%$ range from nominal using the VOUT_TRIM command over the Power management bus.

The VOUT_TRIM command is used to apply a fixed offset voltage to the output voltage command value using the "Linear" mode with the exponent fixed at –10 (decimal). The value of the offset voltage is given by

$$V_{OUT(offset)} = VOUT _TRIM \times 2^{-10}$$

This offset voltage is added to the voltage set through the divider ratio and nominal VREF to produce the trimmed output voltage. The valid range in two's complement for this command is –4000h to 3FFFh. The high order two bits of the high byte must both be either 0 or 1. If a value outside of the +/-25% adjustment range is given with this command, the module will set its output voltage to the nominal value (as if VOUT_TRIM had been set to 0), assert SMBALRT#, set the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.

OUTPUT VOLTAGE MARGINING USING THE POWER MANAGEMENT BUS

The module can also have its output voltage margined via Power management bus commands. The command VOUT_MARGIN_HIGH sets the margin high voltage, while the command VOUT_MARGIN_LOW sets the margin low voltage. Both the VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW commands use the "Linear" mode with the exponent fixed at -10 (decimal). Two bytes are used for the mantissa with the upper bit [7] of the high byte fixed at 0. The actual margined output voltage is a combination of the VOUT_MARGIN_HIGH or VOUT_MARGIN_LOW and the VOUT_TRIM values as shown below.

$$V_{OUT(MH)} =$$

$$(VOUT_MARGIN_HIGH + VOUT_TRIM) \times 2^{-10}$$

$$V_{OUT(ML)} =$$

$$(VOUT_MARGIN_LOW + VOUT_TRIM) \times 2^{-10}$$



Note that the sum of the margin and trim voltages cannot be outside the ±25% window around the nominal output voltage. The data associated with VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW can be stored to non-volatile memory using the STORE DEFAULT ALL command.

The module is commanded to go to the margined high or low voltages using the OPERATION command. Bits [5:2] are used to enable margining as follows:

00XX : Margin Off

0101 : Margin Low (Ignore Fault)
0110 : Margin Low (Act on Fault)
1001 : Margin High (Ignore Fault)
1010 : Margin High (Act on Fault).

POWER MANAGEMENT BUS ADJUSTABLE OVERCURRENT WARNING

The SLDN-40E1Ax module can provide an overcurrent warning via the Power management bus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at –1 (decimal). The upper four bits of the mantissa are fixed at 0 while the lower seven bits are programmable with a default value of 54A.The resolution of this warning limit is 500mA. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

TEMPERATURE STATUS VIA POWER MANAGEMENT BUS

The SLDN-40E1Ax module can provide information related to temperature of the module through the STATUS_TEMPERATURE command. The command returns information about whether the pre-set over temperature fault threshold and/or the warning threshold have been exceeded.

POWER MANAGEMENT BUS ADJUSTABLE OUTPUT OVER AND UNDER VOLTAGE PROTECTION

The SLDN-40E1AX module has output over and under voltage protection capability. The Power management bus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold from four possible values: 108%, 110%, 112% or 115% of the commanded output voltage. The command VOUT_UV_FAULT_LIMIT sets the threshold that causes an output under voltage fault and can also be selected from four possible values: 92%, 90%, 88% or 85%. The default values are 112% and 88% of commanded output voltage. Both commands use two data bytes formatted as two's complement binary integers. The "Linear" mode is used with the exponent fixed to –10 (decimal) and the effective over or under voltage trip points given by:

$$\begin{split} V_{OUT(OV_REQ)} &= (VOUT_OV_FAULT_LIMIT) \times 2^{-10} \\ V_{OUT(UV_REQ)} &= (VOUT_UV_FAULT_LIMIT) \times 2^{-10} \end{split}$$

Values within the supported range for over and undervoltage detection thresholds will be set to the nearest fixed percentage. Note that the correct value for VOUT_SCALE_LOOP must be set in the module for the correct over or under voltage trip points to be calculated.

In addition to adjustable output voltage protection, the 40A Digital module can also be programmed for the response to the fault. The VOUT_OV_FAULT RESPONSE and VOUT_UV_FAULT_RESPONSE commands specify the response to the fault. Both these commands use a single data byte with the possible options as shown below.

- 1. Continue operation without interruption (Bits [7:6] = 00, Bits [5:3] = xxx).
- 2. Continue for four switching cycles and then shut down if the fault is still present, followed by no restart or continuous restart (Bits [7:6] = 01, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).





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- 3. Immediate shut down followed by no restart or continuous restart (Bits [7:6] = 10, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 4. Module output is disabled when the fault is present and the output is enabled when the fault no longer exists (Bits [7:6] = 11, Bits [5:3] = xxx).

Note that separate response choices are possible for output over voltage or under voltage faults.

POWER MANAGEMENT BUS ADJUSTABLE INPUT UNDERVOLTAGE LOCKOUT

The SLDN-40E1AX module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command, possible values are 3.5 to 14 V in 0.5 V steps. For the VIN_OFF command, possible values are 3 V to 14 V in 0.5 V steps. If other values are entered for either command, they will be mapped to the closest of the allowed values.

Both the VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes. The upper five bits represent the exponent (fixed at -2) and the remaining 11 bits represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.

POWER GOOD

The SLDN-40E1Ax module provides a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The PGOOD thresholds are user selectable via the Power management bus (the default values are as shown in the Feature Specifications Section). Each threshold is set up symmetrically above and below the nominal value. The POWER_GOOD_ON command sets the output voltage level above which PGOOD is asserted (lower threshold). For example, with a 1.2 V nominal output voltage, the POWER_GOOD_ON threshold can set the lower threshold to 1.14 or 1.1 V. Doing this will automatically set the upper thresholds to 1.26 or 1.3 V.

The POWER_GOOD_OFF command sets the level below which the PGOOD command is de-asserted. This command also sets two thresholds symmetrically placed around the nominal output voltage. Normally, the POWER_GOOD_ON threshold is set higher than the POWER_GOOD_OFF threshold.

Both POWER_GOOD_ON and POWER_GOOD_OFF commands use the "Linear" format with the exponent fixed at -10 (decimal). The two thresholds are given by y

$$\begin{aligned} V_{OUT(PGOOD_ON)} &= (POWER_GOOD_ON) \times 2^{-10} \\ V_{OUT(PGOOD_OFF)} &= (POWER_GOOD_OFF) \times 2^{-10} \end{aligned}$$

Both commands use two data bytes with bit [7] of the high byte fixed at 0, while the remaining bits are r/w and used to set the mantissa using two's complement representation. Both commands also use the VOUT_SCALE_LOOP parameter so it must be set correctly. The default value of POWER_GOOD_ON is set at 1.1035V and that of the POWER_GOOD_OFF is set at 1.08V. The values associated with these commands can be stored in non-volatile memory using the STORE_DEFAULT_ALL command.

The PGOOD terminal can be connected through a pullup resistor (suggested value 100K) to a source of 5VDC or lower.

MEASUREMENT OF OUTPUT CURRENT, OUTPUT VOLTAGE AND INPUT VOLTAGE

The SLDN-40E1Ax module is capable of measuring key module parameters such as output current and voltage and input voltage and providing this information through the Power management bus interface. Roughly every 200 μ s, the module makes 16 measurements each of output current, voltage and input voltage. Average values of these 16 measurements are then calculated and placed in the appropriate registers. The values in the registers can then be read using the Power management bus interface.



MEASURING OUTPUT CURRENT USING THE POWER MANAGEMENT BUS

The module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT_CAL_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA.

The READ_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11th bit fixed at 0 since only positive numbers are considered valid.

Note that the current reading provided by the module is not corrected for temperature. The temperature corrected current reading for module temperature TModule can be estimated using the following equation:

$$I_{OUT,CORR} = \frac{I_{READ_OUT}}{1 + [(T_{IND} - 30) \times 0.00393]}$$

where IOUT_CORR is the temperature corrected value of the current measurement, I¬READ_OUT is the module current measurement value, TIND is the temperature of the inductor winding on the module. Since it may be difficult to measure TIND, it may be approximated by an estimate of the module temperature.

MEASURING OUTPUT VOLTAGE USING THE POWER MANAGEMENT BUS

The SLDN-40E1Ax module can provide output voltage information using the READ_VOUT command. The command returns two bytes of data all representing the mantissa while the exponent is fixed at -10 (decimal).

During manufacture of the module, offset and gain correction values are written into the non-volatile memory of the module. The command VOUT_CAL_OFFSET can be used to read and/or write the offset (two bytes consisting of a 16-bit mantissa in two's complement format) while the exponent is always fixed at -10 (decimal). The allowed range for this offset correction is -125 to 124mV. The command VOUT_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

$$V_{OUT}(Final) = [V_{OUT}(Initial) \times (1 + VOUT _CAL _GAIN)] + VOUT _CAL _OFFSET$$

MEASURING INPUT VOLTAGE USING THE POWER MANAGEMENT BUS

The SLDN-40E1Ax module can provide output voltage information using the READ_VIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data form the two's complement representation of the mantissa which is fixed at –5 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.





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During module manufacture, offset and gain correction values are written into the non-volatile memory of the module. The command VIN_CAL_OFFSET can be used to read and/or write the offset - two bytes consisting of a five-bit exponent (fixed at -5) and a11-bit mantissa in two's complement format. The allowed range for this offset correction is -2 to 1.968V, and the resolution is 32mV. The command VIN_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

$$V_{IN}(Final) =$$

$$[V_{IN}(Initial) \times (1 + VIN _CAL _GAIN)] + VIN _CAL _OFFSET$$

READING THE STATUS OF THE MODULE USING THE POWER MANAGEMENT BUS

The SLDN-40E1AX module supports a number of status information commands implemented in Power management bus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged.

STATUS_BYTE: Returns one byte of information with a summary of the most critical device faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Low Byte

BIT POSITION	FLAG	DEFAULT VALUE
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0



High Byte

BIT POSITION	FLAG	DEFAULT VALUE
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	X	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	VOUT OV Fault	0
6	X	0
5	X	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	OT Fault	0
6	OT Warning	0
5	Χ	0
4	X	0
3	Χ	0
2	X	0
1	Χ	0
0	X	0

STATUS_CML: Returns one byte of information relating to the status of the module's communication related faults.





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BIT POSITION	FLAG	DEFAULT VALUE
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	X	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR_VIN_MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR_VOUT_MIN: Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614)

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (000101 or 000100 corresponds to the positive and negative logic versions of the SLDN-40E1Ax series of module), while bits [7:3] of the High Byte indicate the revision number of the module.

Low Byte

BIT POSITION	FLAG	DEFAULT VALUE
7:2	Module Name	000110
1:0	Reserved	10

High Byte

BIT POSITION	FLAG	DEFAULT VALUE
7:3	Module Revision Number	None
2:0	Reserved	000



16. SUMMARY OF SUPPORTED POWER MANAGEMENT BUS COMMANDS

Please refer to the Power management bus 1.1 specification for more details of these commands. Table $6\,$

HEX CODE	COMMAND	BRIEF DESCRIPTION	ON								NON- VOLATILE MEMORY STORAGE		
		Turn Module on o	r off. A	lso use	d to ma	rgin the	e outpu	t volta	ge				
		Format	Unsi	gned B	inary								
0.4	OPERATION	Bit Position	7	6	5	4	3	2	1	0			
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r			
		Function	On	Χ	Marg	in		1	Х	Х			
		Default Value	0	0	0	0	0	0	Х	Х			
		Configures the Of	า										
		and Power manag	gement	bus co	mmand	ds							
		Format	Unsig	ned Bir	nary								
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	YES		
		Access	r	r	r	r/w	r/w	r/w	r/w	r			
		Function	Χ	Χ	Χ	pu	cmd	cpr	pol	сра			
		Default Value	0	0	0	1	0	1	1	1			
00	CLEAR FALLEC	Clear any fault bit	ts that	may ha	ve beer	n set, a	lso rele	ases th	he SME	BALERT:	#		
03	CLEAR_FAULTS	signal if the device											
		Used to control v	vriting t	o the n	nodule	via Pov	ver ma	nagem	ent bus	s. Copie	s		
		the current regist	er setti	ng in tl	ne mod	ule wh	ose co	mmanc	d code	matche	s		
		the value in the data byte into non-volatile memory (EEPROM) on the module											
		Format											
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	х	Х	х	х	х			
		Function	bit7	bit6	bit5	Χ	Χ	Χ	Х	Х			
		Default Value	0	0	0	Χ	Χ	Χ	Χ	Х			
10	WRITE_PROTECT	Bit5: 0 - Enables	all write	es as pe	ermitted	in bite	or bit7			•	YES		
		1 - Disables	all write	es exce	pt the \	NRITE_	PROTE	ECT, O	PERAT	ION			
		and ON_	OFF_C	ONFIG	(bit 6 a	nd bit7	must b	oe 0)					
		Bit 6: 0 - Enables											
		1 – Disables			•		_		T and				
		OPERAT			,			,					
		Bit7: 0 – Enables											
		1 – Disables			•	he WRI	TE_PR	OTECT	comm	and			
		(bit5 and			,								
11	STORE_DEFAULT_ALL	Copies all current	•		•						´		
		(EEPROM) on the module. Takes about 50ms for the command to execute. Restores all current register settings in the module from values in the module											
12	RESTORE_DEFAULT_ALL		•		•	ine mo	uule Iro	ııı value	es in the	e moaule	=		
		non-volatile memory Copies the curre	, ,			the m	adula :	uhooo	commo	nd cod	1		
		matches the value	_		-								
		the module	o iii tile	, uala l	yı c iiill	J 11011-\	Joiatile	i i i c i i i i i	у (шшг	i iOivi) Oi	Ί		
13	STORE_DEFAULT_CODE	Bit Position	7	6	5	4	3	2	1	0			
		Access	w	w	w	W	w	w	w	w			
						VV	VV	VV	vv	Ivv			
		Function Command code											



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HEX CODE	COMMAND	BRIEF DESCRIPTION									NON- VOLATILE MEMORY STORAGE
1.4	DESTADE DEFAULT CODE	Restores the current matches the value memory (EEPRON	in the								
14	RESTORE_DEFAULT_CODE	Bit Position	7	6	5	4	3	2	1	0	
		Access	W	W	W	W	W	W	W	W	
		Function	Comm	nand co	ode						
		The module has N cannot be change		et to L	inear ar	nd Expo	onent s	set to -1	0. The	se values	5
00	VOLT MODE	Bit Position	7	6	5	4	3	2	1	0	
20	VOUT_MODE	Access	r	r	r	r	r	r	r	r	
		Function	Mode			Expon	ent				
		Default Value	0	0	0	1	0	1	1	0	
		Apply a fixed offset is fixed at -10.	et volta	ge to th	ne outp	ut volta	ge cor	nmand	value. E	Exponen	t
		Format	Linear	, two's	comple	ement b	oinary				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r	r/w	r/w	r/w	r/w	r/w	r/w	
22	VOUT_TRIM	Function	High E	Byte			•	•	•	•	YES
	_	Default Value	0	0	0	0	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	Low B	yte							
		Default Value	0	0	0	0	0	0	0	0	
		Sets the target vo	ltage f	or març	gining t	he outp	out hiç	gh. Exp	onent is	s fixed a	t
		Format	Linear	, two's	comple	ement b	oinary				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
25	VOUT_MARGIN_HIGH	Function	High E	Byte						•	YES
		Default Value	0	0	0	0	0	1	0	1	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	Low B	yte							
		Default Value	0	1	0	0	0	1	1	1	
		Sets the target vol	tage fo	r margi	ning the	e outpu	t low. I	Expone	nt is fixe	ed at	-
		Format	Linear	, two's	comple	ement b	oinary				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
26	VOUT_MARGIN_LOW	Function	High E	Byte							YES
	O VOUT_IVIANGIN_LOW	Default Value	0	0	0	0	0	1	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	Low B	yte			_				
		Default Value	0	1	0	1	0	0	0	1	



HEX CODE	COMMAND	BRIEF DESCRIPTI	ON								NON- VOLATILE MEMORY STORAGE
		Sets the scaling o	of the o	utput v	oltage -	- equal	to the f	eedbac	ck resis	tor divid	
		Format	Linea	r. two's	comp	lement	binarv				7
		Bit Position	7	6	5	4	3	2	1	0	1
		Access	r	r	r	r	r	r	r/w	r/w	1
29	VOUT_SCALE_LOOP	Function	Expo	nent	1			Mar	ntissa		YES
		Default Value	1	0	1	1	1	0	0	1	1
		Bit Position	7	6	5	4	3	2	1	0	1
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1
		Function	Manti	issa							1
		Default Value	0	0	0	0	0	0	0	0	1
		Sets the value of	input v	oltage	at whic	h the n	nodule	turns o	n		
		Format	Linea	r, two's	comp	lement	binary] [
		Bit Position	7	6	5	4	3	2	1	0	11
		Access	r	r	r	r	r	r	r	r	1
25	VINL ON	Function	Expo	nent		•	•	Mar	ntissa		YES
35	VIN_ON	Default Value	1	1	1	1	0	0	0	0	1115
		Bit Position	7	6	5	4	3	2	1	0	11
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	11
		Function	Manti	issa]
		Default Value	0	0	0	0	1	1	1	0	11
		Sets the value of	input v	oltage	at whic	h the n	nodule	turns o	ff		
		Format	Linea	r, two's	comp	lement	binary]
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	11
36	VIN_OFF	Function	Expo	nent				Mar	ntissa		YES
30	VIIV_011	Default Value	1	1	1	1	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w]
		Function	Manti	issa] [
		Default Value	0	0	0	0	1	1	0	0	
		Returns the value	e of the	gain c	orrection	n term	used t	o corre	ect the	measure	ed
		output current	ı								_
		Format				lement					11
		Bit Position	7	6	5	4	3	2	1	0	11
		Access	r	r	r	r	r	r	r	r/w	11
38	38 IOUT_CAL_GAIN	Function	Expo	_	1-	1_		_	ntissa	1_	YES
		Default Value	1	0	0	0	1	0	0	0	<u> </u>
		Bit Position	7	6	5	4	3	2	1	0	11
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	11
		Function	Manti								11
		Default Value	V: Va	riable b	ased o	n facto	ry calib	ration			



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HEX CODE	COMMAND		RIEF DESCRIPTION Seturns the value of the offset correction term used to correct the measure									
			of the	offset c	orrectio	n term	used to	o corre	ct the n	neasured	d	
		output current										
		Format	_	, two's		ement b	inary					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r/w	r	r		
39	IOUT_CAL_OFFSET	Function	Expon	ent				Mant	issa		YES	
		Default Value	1	1	1	0	0	1	1	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function										
		Default Value	V: Var	iable ba	ased or	factory	y calibr	ration				
		Sets the voltage leads to suggested value output voltage. Voltage.	alue sh /alues	own fo	or 1.2V 108%	o. Sho , 110%	uld be 6, 112	chang	ed for	differen	t	
		Format										
		Bit Position	7	6	5	4	3	2	1	0		
40	VOUT_OV_FAULT_LIMIT	Access	r 	r/w	r/w	r/w	r/w	r/w	r/w	r/w	YES	
		Function	High E	_	1_	1_	1_	1.	1_			
		Default Value	0	0	0	0	0	1	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	Low B	syte		1	T		1	_		
		Default Value	0	1	1	0	0	0	0	0		
		Instructs the mo overvoltage fault	dule o	n what	action	to ta	ke in	respon	se to a	a outpu	t	
		Format	Unsig	ned Bir	ary							
44	VOLIT OV FALILT DESPONSE	Bit Position	7	6	5	4	3	2	1	0	VEC	
41	VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	YES	
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	х	х		
		Default Value	1	1	1	1	1	1	0	0		
		Sets the voltage level for an output undervoltage fault. Exponent is fixed at - 10. Suggested value shown for 1.2Vo. Should be changed for different output voltage. Values can be 92%, 90%, 88% or 85% of output voltage. Format Linear, two's complement binary										
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
44	VOUT_UV_FAULT_LIMIT	Function	High E	1	<u> </u>	L	<u> </u>	1		1	YES	
		Default Value	0	0	0	0	0	1	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	Low B		1.,	1	1.,	1.,	1.7.	1.7.**		
		Default Value	0	0	1	1	1	0	0	1		
		-cidalt value	1		<u> ' </u>	1'	l'	ľ	٠	'		



HEX CODE	COMMAND	BRIEF DESCRIPT	ION								NON- VOLATILE MEMORY STORAGE
		Instructs the modu undervoltage fault	le on w	hat action	on to tal	ke in res	ponse	to a out	tput		
		Format	Linciar	ned Bina	n (
		Bit Position	7	6	1 y 5	4	3	2	1	0	
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	YES
		Function	RSP [1]	RSP [0]				X	X	X	
		Default Value	0	0	0	0	0	1	0	0	
		Sets the output over	_	-		-	-		Ισ	U	
		Format				nent bin		angeuj			
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	Expon	1	<u>'</u>	l'	<u>'</u>	Mant	isea	<u>'</u>	
46	IOUT_OC_FAULT_LIMIT	Default Value	1	1	1	1	1	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	Mantis	1	ļi.	I	ļi .	l'	<u> </u>	li.	
		Default Value	0	1 1	1	0	1	1 1	1	0	
			_	· .		_	!	!	<u> </u>	U	
		Sets the output over									
			7		 	nent bin		Io.	1	10	
		Bit Position	1	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	<u> r </u>	r	
4A	IOUT_OC_WARN_LIMIT	Function	Expon			1.	L	Mant		10	YES
		Default Value	1	1	1	1	1	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	Mantis			1 -			1 -		
		Default Value	0	1	1	0	1	1	0	0	
		Sets the output vol is fixed at -10.	_					asserte	d high.	Exponen	t
		Format				nent bir					
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
5E	POWER_GOOD_ON	Function	High E						1		YES
		Default Value	0	0	0	0	0	1	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	Low B								
		Default Value	0	1	1	0	1	0	1	0	
		Sets the output v Exponent is fixed a	ıt -10.					oin is (de-asse	rted low	'. <u> </u>
		Format				nent bir					
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
5F	POWER_GOOD_OFF	Function	High E	yte							YES
		Default Value	0	0	0	0	0	1	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
I II-		Function	Low B	yte							
		Default Value	0	1	0	1	0	0	1	0	



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HEX												NON- VOLATILE
CODE	COMMAND	BRIEF DESCRIPTI	ON									MEMORY
												STORAGE
		Sets the rise time o	f the ou	ıtput vo	Itage	durin	ıg staı	tup				
		Format	Linear,	two's	compl	eme	nt bina	ary				
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r/w	
61	TON_RISE	Function	Expone	ent					Manti	issa	_	YES
01	TOTA_THOE	Default Value	1	1	1	0		0	0	0	0	120
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r/w	r/w	r/w	r/	W	r/w	r/w	r/w	r/w	
		Function	Mantis	sa								
		Default Value	0	0	1	0		1	0	1	0	
		Returns one byte of		ation wi		umm	nary of	f the m	ost criti	cal mod	dule fault	s
		Format Bit Position	7	ea Bina	ary 5	4	ı	3	2	1	0	
78	STATUS_BYTE	Access	r	r	r	4		r	r	r	r	
1'0	OIATOS_BITE				r VOU	T IC		r VIN_U		1	OTHE	
		Flag	X	OFF	_OV	0	С	V	TEMP		R	
		Default Value	0	0	0	0		0	0	0	0	
		Returns two bytes of information with a summary of the module's fault/warning conditions										g
		Format	Linear,	two's	compl	emei	nt bina	ary				
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
79	STATUS_WORD	Flag	VOUT	IOUT_ OC	Х	Х		PGOO D	Х	X	Х	
		Default Value	0	0	0	0		0	0	0	0	
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
		Flag	Х	OFF	VOU _OV	T IC		VIN_U V	TEMP	CML	OTHE R	
		Default Value	0	0	0	0		0	0	0	0	
		Returns one byte or related faults	of inforn	nation v	with th	ne st	atus d	of the r	nodule'	s outpu	ıt voltag	е
		Format	Unsign	ed Bina	ary							
7A	STATUS_VOUT	Bit Position	7			5	4		3 2	1	0	
		Access	r		r I	r	r		r r	r	r	
		Flag	VOUT_	OV	X 2	Χ	VOU	Γ_UV	х х	X	Х	
		Default Value	0		0	0	0		0 0	0	0	
		Returns one byte or related faults	of inforn	nation v	with th	ne st	atus o	of the r	nodule'	s outp	ut curren	t
		Format	Unsign	ed Bina	ary							
7B	STATUS_IOUT	Bit Position	7	6	5	4	3			2	1 0	
		Access	r	r	r	r	r			r	r r	
		Flag	IOUT_0	OC X	X	Χ	IOU	T_OC_\	WARN	Х	X X	
		Default Value	0	0	0	0	0			0	0 0	



HEX CODE	COMMAND	BRIEF DESCRIPTION	BRIEF DESCRIPTION										
		Returns one byte related faults	of infor	matio	n with th	ne stat	us o	f the	modu	le's tem	perature		
		Format	Unsig	ned Bi	nary								
7D	STATUS_TEMPERATURE	Bit Position	7		6		5	4	3	2 1	0		
		Access	r		r		r	r	r	r r	r		
		Flag	OT_F	AULT	OT_W	ARN	Χ	Х	Х	X X	Х		
		Default Value	0		0		0	0	0	0 0	0		
		Returns one by			nation	with	the	stati	us of	f the r	nodule's	s	
		communication re											
		Format	Unsig			1							
		Bit Position	7		6	5	4	3	2	1	0		
7E	STATUS_CML	Access	r		r	r	r	r	r	r	r		
		Flag	Invalid Comm		Invalid Data	PEC Fail	х	х	х	Other Comm Fault	×		
		Default Value	0		0	0	0	0	0	0	0		
		Returns the value							nodule	9			
		Format	Linear	, two's	s compl	emen	t bina						
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r		r	r	r		
88	B READ_VIN	Function	Expor	ent		_			Man	tissa			
	112.05_111	Default Value	1	1	0	1	1		0	0	0		
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r		r	r	r		
		Function	Mantis							1			
		Default Value	0	0	0	0	0		0	0	0		
		Returns the value -10.							. Ехр	onent is	s fixed at		
		Format			compl					T			
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r		r	r	r		
8B	READ_VOUT	Function	Mantis		10	10	10		0	10			
		Default Value	0	0	0	0	0		0	0	0		
		Bit Position	7	6 r	5 r	4 r	3 r		2 r	1	0		
		Access Function	r Mantis			lı	ſ		1	r	r		
		Default Value	0	0 0	0	0	0		0	0	0		
		Returns the value							J	U	J		
		Format			s compl								
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r		<u>r</u>	r	r		
_		Function	Expor		<u></u>				-	tissa			
8C	READ_IOUT	Default Value	1	1	1	0	0		0	0	0		
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r		r	r	r		
	I	Function	Mantis	ssa						-1	-		
		Default Value	0	0	0	0	0		0	0	0		



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HEX CODE	COMMAND	BRIEF DESCRIPTION									NON- VOLATILE MEMORY STORAGE
		Returns one byte			module	e is cor	npliant	to Pow	ver mar	nagemen	t
		bus Spec. 1.1 (rea									
00	POWER MANAGEMENT	Format	Unsig	ned Bir	nary						VEC
98	BUS_REVISION	Bit Position	7	6	5	4	3	2	1	0	YES
	_	Access	r	r	r	r	r	r	r	r	
		Default Value	0	0	0	1	0	0	0	1	
		Returns the minir (read only)						specifie	ed to o	perate a	t
		Format				ement l				-	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
A0	MFR_VIN_MIN	Function	Expor	ent				Man	tissa	_	YES
		Default Value	1	1	1	1	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	Mantis	ssa					•		
		Default Value	0	0	0	0	1	1	0	0	
		Returns the minim	num ou	tout vo	ltago n	occiblo	from t	ho mod	lulo (roc	nd only)	
		Format				ement l		ne mou	iule (rea	iu Orliy)	
		Bit Position						lo.	14	10	
			7	6	5	4	3	2	1	0	
	MFR_VOUT_MIN	Access	r	r	r	r	r	r	r	r	
A4		Function	Mantis		-	1_	1-	1_	Τ.	1_	YES
		Default Value	0	0	0	0	0	0	1	0	1.00
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	Mantis			•		_	_		
		Default Value	0	1	1	0	0	1	1	0	
		Returns module n	ame in	formati	on (rea	d only)					
		Format		ned Bir							
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
l_		Function	Reser	ved		1	1	1	1	1	
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	R	r	r	r	
		Function	Modu	le Nam	e 	1.	1	1.	Rese	erved	
		Default Value	0	0	To To	1	0	0	0	n	
		Applies an offset t	Ŭ	1-						U	+
		errors in module r +124mV). Expone	neasure ent is fi	ements xed at ·	of the		voltag				
	04 VOUT_CAL_OFFSET	Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r	r	r	r	r	r	r	
D4		Function	Mantis	l _i	1'	1'	<u> </u> '	i'	Ţı.	11	YES
			V		lo.	0	0	lo.	0	0	
		Default Value	7	0	0	4	_	2	_	0	
		Bit Position	/	6	5		3		1		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	Mantis		h.,	ls ,		h.,	1	1.7	
		Default Value	V	V	V	V	V	V	V	V	



HEX CODE	COMMAND	BRIEF DESCRIPTION	RIEF DESCRIPTION									
		Applies a gain cogain errors in moo										
		Format	Linear	, two's	comple	ement b	oinary					
		Bit Position	7	6	5	4	3	2	1	0		
D.	VOLIT CAL CAIN	Access	r	r	r	r	r	r/w	r	r		YES
D5	VOUT_CAL_GAIN	Function	Expon	ent				Man	itissa			YES
		Default Value	1	1	0	0	0	0	0	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w		
		Function	Mantis	ssa				•		•		
		Default Value	٧	٧	٧	V	٧	V	٧	V		
D6	VIN_CAL_OFFSET	Applies an offset offset errors in m +1.968V) Format Bit Position Access Function Default Value Bit Position Access Function Default Value Applies a gain con	Linear 7 r Expon 1 7 r Mantis	measu r, two's 6 r nent 1 6 r ssa 0	comple 5 r	s of the ement to 4 r	oinary 3 r V 3 r/w	2 r/w Man 0 2 r/w	ge (bet	0	/ and	YES
D7	VIN_CAL_GAIN	errors in module r Format Bit Position Access Function Default Value Bit Position Access Function Default Value	neasur	ements r, two's 6 r nent 1 6 r	of the	input v	oltage	(between 2 r/w			-	YES



17. THERMAL CONSIDERATIONS

The SLDN-40E1Ax power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 30. The preferred airflow direction for the module is in Figure 31.

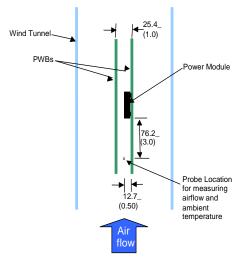


Figure 30. Thermal Test Setup

The thermal reference points, Tref used in the specifications are also shown in Figure 30. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x lo,max).

Please refer to the Application Note "Thermal Characterization Process for Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

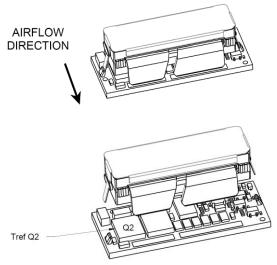


Figure 31. Preferred airflow direction and location of hot spot of the module (Tref)



18. EXAMPLE APPLICATION CIRCUIT

Requirements:

Vin: 12 V 1.8 V Vout:

lout: 30 A max., worst case load transient is from 20 A to 30 A ∆Vout: 1.5% of Vout (27 mV) for worst case load transient

Vin, ripple 1.5% of Vin (180 mV, p-p)

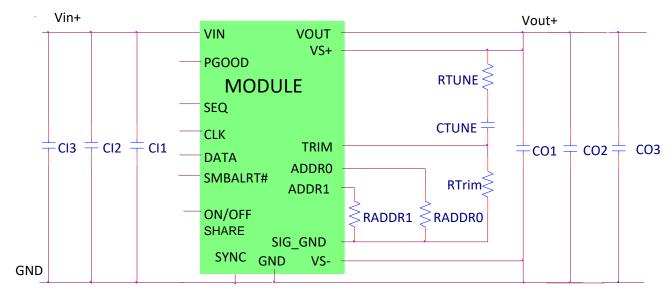


Figure 32.

CI1	Decoupling cap - 1x0.01 μ F/16 V ceramic capacitor (e.g. Murata LLL185R71E103MA01)
CI2	3x22 μF/16 V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)
CI3	470 μF/16 V bulk electrolytic
CO1	Decoupling cap - 1x0.01 μF/16 V ceramic capacitor (e.g. Murata LLL185R71E103MA01)
CO2	4 x 47 μF/6.3 V ceramic capacitor (e.g. Murata GRM31CR60J476ME19)
CO3	6 X330 μF/6.3 V Polymer (e.g. Sanyo Poscap)
CTune	5600 pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune	$220~\Omega$ SMT resistor (can be 1206, 0805 or 0603 size)
R_{Trim}	10 kΩ SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

Notes: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.

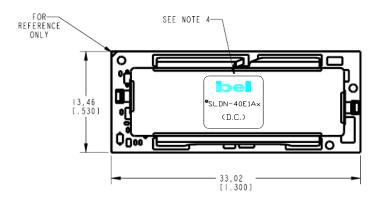


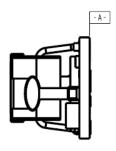
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19. MECHANICAL DIMENSIONS

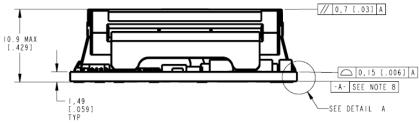
OUTLINE





END VIEW

TOP VIEW



.051 - .228 REF [.002 - .009] SOLDER PLATING THICKNESS ON LAND GRID ARRAY I9 PLCS DETAIL A SCALE 20.000

Figure 33.

Notes:

Dimensions are in mm [inch].

Tolerances: x.x mm \pm 0.5 mm [\pm 0.02 inch] [unless otherwise indicated]

x.xx mm \pm 0.25 mm [\pm 0.010 inch]

PIN DEFINITIONS

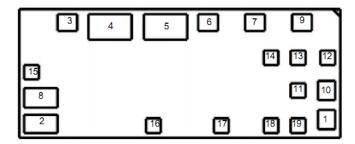


Figure 34. Pins

PIN	FUNCTION	PIN	FUNCTION
1	ON/OFF	11	SIG_GND
2	VIN	12	VS-
3	SEQ	13	CLK
4	GND	14	DATA
5	VOUT	15	SYNC
6	TRIM	16	PG
7	VS+	17	SMBALERT#
8	GND	18	ADDRESS 0
9	SHARE	19	ADDRESS 1
10	GND		

RECOMMENDED PAD LAYOUT

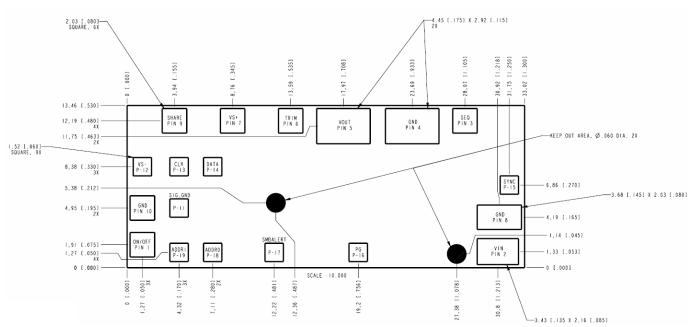


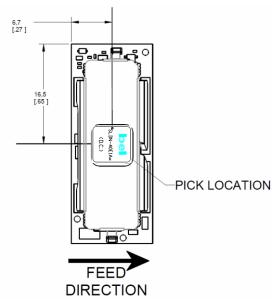
Figure 35. Recommended pad layout



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20. PACKAGING DETAILS

The SLDN-40E1Ax modules are supplied in tape & reel as standard. All Dimensions are in mm [inch].



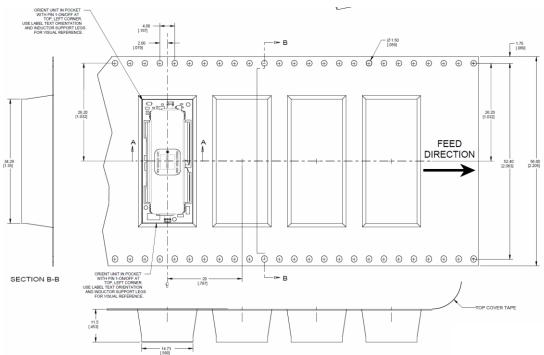


Figure 36. Packaging details

Reel Dimensions:

Outside Dimensions: 330.2 mm (13.00) Inside Dimensions: 177.8 mm (7.00") Tape Width: 56.00 mm (2.205")



21. SURFACE MOUNT INFORMATION

PICK AND PLACE

The SLDN-40E1Ax modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

NOZZLE RECOMMENDATIONS

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3 mm. The max. nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.

BOTTOM SIDE / FIRST SIDE ASSEMBLY

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

LEAD FREE SOLDERING

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

PB-FREE REFLOW PROFILE

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 37. Soldering outside of the recommended profile requires testing to verify results and performance.

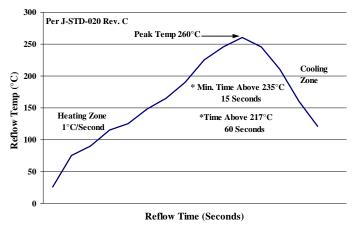


Figure 37. Recommended linear reflow profile using Sn/Ag/Cu solder.

MSL RATING

The SLDN-40E1Ax modules have a MSL rating of 2A.



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STORAGE AND HANDLING

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of \leq 30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.

POST SOLDER CLEANING AND DRYING CONSIDERATIONS

Post solder cleaning is usually the final circuit board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).



22. REVISION HISTORY

DATE	REVISION	CHANGES DETAIL	APPROVAL
2012-09-11	Α	First release	HL.Lu
2012-09-19	В	Add the patents info.	HL.Lu
2012-12-11	С	Update paralleling with active load sharing.	HL.Lu
2013-07-16	D	Update output capacitance, synchronization frequency range, safety considerations, analog output voltage programming, over temperature protection, Tunable Loop, measuring output current using the Power management bus, thermal considerations, example application, MSL rating; add transient waveforms.	XF.Jiang
2015-07-10	E	Update part selection, absolute maximum ratings, output specifications, general specifications, digital interface specification, remote on/off, analog voltage margining, output voltage adjustment, paralleling with active load sharing section using the Power management bus, Power management bus adjustable overcurrent warning, reading the statues of the module using the Power management bus, summary of supported Power management bus commands, thermal considerations, packaging details, and add load transient considerations.	XF.Jiang
2021-08-17	AF	Add object ID. Update to new format. Update safety certificate and altitude. Change PMbus to power management bus.	XF.Jiang

For more information on these products consult: tech.support@psbel.com

NUCLEAR AND MEDICAL APPLICATIONS - Products are not designed or intended for use as critical components in life support systems, equipment used in hazardous environments, or nuclear control systems.

TECHNICAL REVISIONS - The appearance of products, including safety agency certifications pictured on labels, may change depending on the date manufactured. Specifications are subject to change without notice.



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