



PET1300-12-054xA is a 1300 Watt AC to DC power-factor-corrected (PFC) power supply that converts standard AC mains power into a main output of 12 VDC for powering intermediate bus architectures (IBA) in high performance and reliability servers, routers, and network switches.

The PET1300-12-054xA meets international safety standards and displays the CE-Mark for the European Low Voltage Directive (LVD).



# **Key Features & Benefits**

- High efficiency up to 94.0%
- Wide input voltage range: 90 264 VAC
- Active power factor correction
- Always-On 10 W standby output (3.3 V)
- Hot-plug capability
- Parallel operation with active current sharing
- Full digital control for circuit loop and power management
- High density design: 30.25 W/in<sup>3</sup>
- Compact form factor: 54.5 x 40.0 x 321.5 mm
- PMBus® Communication Interface for control, programming
- and monitoring
- Fully protected (OTP, OCP, OVP, SCP)
- 4K Bytes of EEPROM for user information
- 2 Status LEDs: FAIL and OK with fault signaling
- Approved to the latest edition of following Safety Standards: UL/CSA 62368-1, IEC / EN 62368-1



## **Applications**

- High Performance Servers
- Networking Switches
- Routers

Disclaimer: PMBus is a registered trademark of SMIF, Inc.



### 1. ORDERING INFORMATION

PET	1300		12		054	х	Α
Product Family	Power Level	Dash	V1 Output	Dash	Width	Airflow	Input
PET Front-Ends	2000 W		12 V		54 mm	N: Normal R: Reverse	A: AC

### 2. OVERVIEW

The PET1300-12-054xA AC/DC power supply is a fully DSP controlled, highly efficient front-end power supply. It incorporates resonance-soft-switching technology and interleaved power trains to reduce component stresses, providing increased system reliability and very high efficiency. With a wide input operational voltage range and minimal linear derating of output power with input voltage and temperature, the PET1300-12-054xA maximizes power availability in demanding server, network, and other high availability applications. The supply is fan cooled and ideally suited for integration with a matching airflow paths.

The PFC stage is an analogue solution; MCU is used to communicate with DSP chip on secondary side.

The DC/DC stage uses soft switching resonant techniques in conjunction with synchronous rectification. An active OR-ing device on the output ensures no reverse load current and hence it is ideally suited for operation in redundant power systems.

The always-on standby output with voltage level (3.3 Volts), provides power to external power distribution and management controllers. It is protected with an active OR-ing device for maximum reliability.

Status information is provided with front-panel LEDs. In addition, the power supply can be controlled and the fan speed set via the I<sup>2</sup>C bus. The I<sup>2</sup>C bus allows full monitoring of the supply, including input and output voltage, current, power, and inside temperatures.

Cooling is managed by a fan controlled by the DSP controller. The fan speed is adjusted automatically depending on the actual power demand and supply temperature and can be overridden through the I<sup>2</sup>C bus.

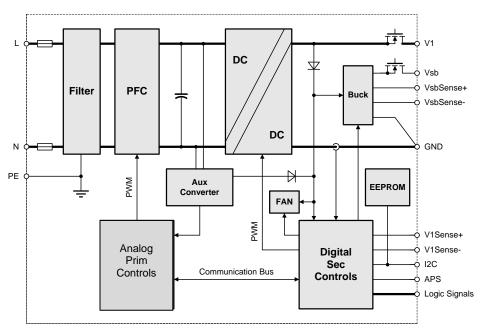


Figure 1. PET1300-12-054xA Block Diagram



# 3. INPUT

General Condition:  $T_A = 0...60$  °C, unless otherwise noted.

PARAME	TER DESCRIPTION / CONDITION MIN NOM MAX L		UNIT			
V <sub>i nom</sub>	Nominal Input Voltage		100		240	VAC
Vi	Input Voltage Ranges	Normal operating (Vi min to Vi max)	90		264	VAC
I <sub>i max</sub>	Max Input Current	Vin = 110 VAC / 60 Hz, Full load			13.6	$A_{rms}$
l <sub>i p</sub>	Inrush Current Limitation	Vi min to Vi max, TNTC = 25 °C			50	Ap
Fi	Input Frequency		47	50/60	63	Hz
PF	Power Factor	$V_{i \text{ nom}}$ , 50 Hz, $> 0.2 I_{1 \text{ nom}}$		0.95		W/VA
$V_{i\ on}$	Turn-on Input Voltage <sup>1</sup>	Ramping up	85		90	VAC
$V_{i  off}$	Turn-off Input Voltage <sup>1</sup>	Ramping down	70		83	VAC
Power	Rated Power <sup>2</sup>	See Figure 2 & Figure 3			1100 1300	W W
		$V_{in}$ = 230 V, 12 V / 21.6 A, 3.3 V / 0.6 A $T_A$ = 25 °C		93.0		
η	Efficiency without Fan	$V_{in}$ = 230 V, 12 V / 54 A, 3.3 V / 1.5 A $T_A$ = 25 °C		94.0		%
		$V_{in}$ = 230 V, 12 V / 108 A, 3.3 V / 3 A $T_A$ = 25 °C		92.0		
T <sub>hold</sub>	Hold-up Time	After last AC zero point, $V_1 > 11.6$ V, $V_{SB}$ within regulation, $V_i = 230$ VAC, $12$ V / $108$ A, $3.3$ V / $3$ A	10			ms

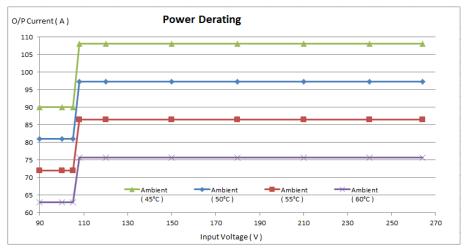


Figure 2. Derating on Iout vs Vin and Ta for PET1300-12-054NA

<sup>&</sup>lt;sup>2</sup> The output power is should be derating as below curve if operation temperature increases from 45°C to 60°C.



Asia-Pacific

Europe, Middle East

<sup>&</sup>lt;sup>1</sup> The Front-End is provided with a minimum hysteresis of 3 V during turn-on and turn-off within the ranges.

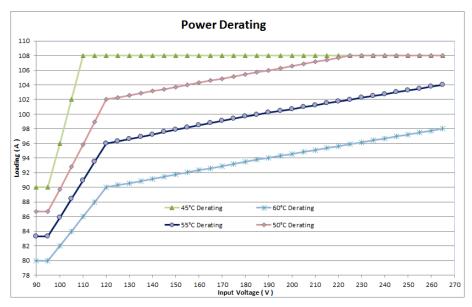


Figure 3. Derating on Iout vs Vin and Ta for PET1300-12-054RA

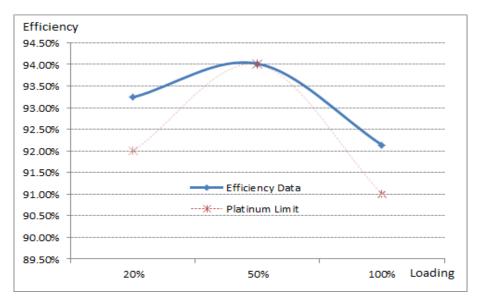


Figure 4. Efficiency Measurement Curve



# 4. OUTPUT

General Condition:  $T_A = 0...60$  °C, unless otherwise noted.

Wain Output V-I         V-I room         Nominal Output Voltage         0.5 · I room, Tamb = 25 °C         12.0         VDC           V1 set         Output Setpoint Accuracy         0.5 · I room, Tamb = 25 °C         -0.5         +0.5         % V1 room           V1 set         Total Regulation         V1 min to V1 inax, 0 to 100% I i room, Tamb to Tamax         -3         +3         % V1 room           P1 room         Nominal Output Power         V1 = 12 VDC         108         26         W1 room           I noom         Nominal Output Current         V1 = 12 VDC, V1n ≥ 108 VAC         108         Acc           V1 room         Output Ripple Voltage         V1 room, 1 room, 20 MHz BW         108         mVp           dV1 tipus         Load Regulation         V1 = V1 room, 0 - 100% I room         60         mV           dV1 tipus         Load Regulation         V1 = V1 room, V1 room         20         mV           dV1 tipus         Line Regulation         When Bus load = 27 A         4.5         A           dW5yn         Dynamic Load Regulation         Iout 10% -60% of full load; 50% -100% of full load; 50% -100% of full load; 50% -100% of V1 room         0.5         1         ms           tacvy         Stan-up Time from AC         3         3         ms           V1 field <th>PARAME</th> <th>TER</th> <th>DESCRIPTION / CONDITION</th> <th>MIN</th> <th>NOM</th> <th>MAX</th> <th>UNIT</th>	PARAME	TER	DESCRIPTION / CONDITION	MIN	NOM	MAX	UNIT
V1 set         Output Setpoint Accuracy         0.5 1 nom, Tamb = 25 °C         −0.5	Main Out	tput V₁					
V1 satt         Output Setpoint Accuracy         -0.5         +0.5         % V1 nom           dV1 tot         Total Regulation         V1 min to V1 max, 0 to 100% In nom, Ta min to Ta max         -3         ±3         % V1 nom           P1 nom         Nominal Output Power         V1 = 12 VDC, V1n ≥ 108 VAC         108         Abc           V1 pp         Output Ripple Voltage         V1 nom, 11 nom, 20 MHz BW         180         mVpp           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% In nom         60         mV           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% In nom         60         mV           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% In nom         60         mV           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% In nom         20         mV           dV2 In nom, 12 Sabs fill—80, between any two units in parallelly         when Bus load < 27 A	V <sub>1 nom</sub>	Nominal Output Voltage	0.5.1 T 0.5.00		12.0		VDC
P1 nom         Nominal Output Power         V1 = 12 VDC         1296         W           I₁ nom         Nominal Output Current         V1 = 12 VDC, Vin ≥ 108 VAC         108         Apc           V₁ pp         Output Ripple Voltage         V₁ nom, I₁ nom, 20 MHz BW         180         mVpp           dV₁ tasal         Load Regulation         V₁ = V₁ nom, I₁ nom, 20 MHz BW         60         mV           dV₁ thre         Line Regulation         V₁ = V₁ nom, 0 - 100% I₁ nom         60         mV           dV₁ thre         Line Regulation         V₁ = V₁ nom, 0 - 100% I₁ nom         20         mV           dI share         Current Sharing (abs (n-t)), between any two units in parallel)         when Bus load < 27 A	$V_{1 \; set}$	Output Setpoint Accuracy	0.3 ·11 nom, 1 amb = 25 · C	-0.5		+0.5	$\%~V_{1~nom}$
In nom	$dV_{1\;tot}$	Total Regulation	$V_{imin}toV_{imax},0to100\%I_{1nom},T_{amin}toT_{amax}$	-3		+3	$\%~V_{1~nom}$
V1 pp Dutput Ripple Voltage         V1 nom, l1 nom, 20 MHz BW         180         mVpp mVp mVp mVp           dV1 Load         Load Regulation         V1 = V1 nom, 0 - 100% l1 nom         60         mV           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% l1 nom         60         mV           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% l1 nom         60         mV           dV1 Line         Line Regulation         V1 = V1 nom, 0 - 100% l1 nom         20         mV           dlshare         Current Sharing (abs (l1-l), between any two (abs (l-l), between any two (l-l), between any two (abs (l-l), between any two (l-l), between any two (abs (l-l), between any two (	P <sub>1 nom</sub>	Nominal Output Power	V <sub>1</sub> = 12 VDC		1296		W
dV1 Load         Load Regulation         V. = V.nom, 0 - 100% Is nom         60         mV           dV1 Line         Line Regulation         V. = V.min V.max         20         mV           dBahare         Current Sharing (abs (irle), between any two units in parallel)         when Bus load ≥ 27 A         4.5         A           dVoyn         Dynamic Load Regulation         lout: 10%60% of full load; 50%100% of full load         -0.6         0.6         V           Trec         Recovery Time         lout: 10%60% of full load; 50%100% of full load         -0.6         0.6         V           tAc V1         Start-up Time from AC         2         s         1         ms           tAc V1         Start-up Time from AC         2         s         11000         μF           Standby Output Vss         Fise Time         V1 = 1090% V1 nom         3         ms         ms           VSB nom         Nominal Output Voltage         0.5 · IsB nom, Tamb = 25 °C         3.3         VDC           VSB set         Output Setpoint Accuracy         0.5 · IsB nom, Tamb = 25 °C         -1         +1         %Vsbnom           PSB nom         Nominal Output Power         VsB = 3.3 VDC, normal airflow         10         W           IsB nom         Nominal Output C	I <sub>1 nom</sub>	Nominal Output Current	V <sub>1</sub> = 12 VDC, Vin ≥ 108 VAC		108		$A_{DC}$
dV1 Line         Line Regulation         Vi =VinninVi max         20         mV           dIshare         Current Sharing (abs (β1-2b), between any two units in parallel)         when Bus load ≥ 27 A when Bus load ≥ 27 A when Bus load < 27 A         4.5         A           dVoyn         Dynamic Load Regulation         bout: 10%60% of full load; 50%100% of full load; 50%100% of full load         -0.6         V           Trec         Recovery Time         du1/dt = 1A/μs, recovery within 1% of V₁ nom         0.5         1         ms           tx cv1         Start-up Time from AC         2         s         1         ms           Ctoad         Capacitive Loading         Ta = 25 °C         11000         μF           Standby Output Vsts           Vs B nom         Nominal Output Voltage         0.5 ·lsg nom, Tamb = 25 °C         3.3         VDC           VsB set         Output Setpoint Accuracy         0.5 ·lsg nom, Tamb = 25 °C         3.3         VDC           VsB set         Total Regulation         V₁ min to V₁ max, 0 to 100% lss nom, Tamin to Ta max         -1.5         +1.5         %Vssnom           PsB nom         Nominal Output Power         VsB = 3.3 VDC, normal airflow         10         W           lss phone         Nominal Output Current         VsB snom, lss nom, 20 MHz BW (See Sect	V <sub>1 pp</sub>	Output Ripple Voltage	$V_{1 \text{ nom}}$ , $I_{1 \text{ nom}}$ , 20 MHz BW			180	mVpp
Current Sharing (abs (in-le), between any two units in parallet)         when Bus load ≥ 27 A when Bus load ≥ 27 A when Bus load ≥ 27 A         4.5 A         A           dVoyn         Dynamic Load Regulation         lout:10%-60% of full load; 50%100% of full load of 10 load; 50%100% of full l	dV <sub>1 Load</sub>	Load Regulation	$V_i = V_{i \text{ nom}}, \text{ 0 - 100\% } I_{1 \text{ nom}}$		60		mV
Start   Clast   Cla	$dV_{1\; Line}$	Line Regulation	$V_i = V_{i  min}V_{i  max}$		20		mV
wints in parallel)         when Bus load < 27 A         5.6         A           dVoyn         Dynamic Load Regulation         lout:10%60% of full load; 50%100% of full load         -0.6         0.6         V           Trec         Recovery Time         dl₁/dt = 1A/μs, recovery within 1% of V₁ nom         0.5         1         ms           tacv1         Start-up Time from AC         2         s           tv1 rise         Rise Time         V₁ = 1090% V₁ nom         3         ms           Cuoad         Capacitive Loading         Ta = 25 °C         11000         μF           Standby Output VsB           VsB nom         Nominal Output Voltage         0.5 ·lsB nom, Tamb = 25 °C         3.3         VDC           VsB set         Output Setpoint Accuracy         0.5 ·lsB nom, Tamb = 25 °C         -1         +1         %V₁ nom           dVsB tot         Total Regulation         V₁ min to V₁ max, 0 to 100% lsB nom, Tamb to Ta max         -1.5         +1.5         %VsB nom           PsB nom         Nominal Output Power         VsB = 3.3 VDC, normal airflow         10         W           VsB pn         Nominal Output Current         VsB = 3.3 VDC, normal airflow         3         ADC           VsB pn         Output Ripple Voltage         VsB nom, lsB n	di .		when Bus load ≥ 27 A			4.5	Α
Trec         Recovery Time         dl <sub>1</sub> /dt = 1A/μs, recovery within 1% of V <sub>1 nom</sub> 0.5         1         ms           t <sub>AC V1</sub> Start-up Time from AC         2         s           t <sub>V1 riss</sub> Rise Time         V <sub>1</sub> = 1090% V <sub>1 nom</sub> 3         ms           C <sub>Load</sub> Capacitive Loading         T <sub>a</sub> = 25 °C         11000         μF           Standby Output Vs <sub>B</sub> VSB nom         Nominal Output Voltage         0.5 ·ls <sub>B nom</sub> , T <sub>amb</sub> = 25 °C         3.3         VDC           V <sub>SB set</sub> Output Setpoint Accuracy         0.5 ·ls <sub>B nom</sub> , T <sub>amb</sub> = 25 °C         -1         +1         %V <sub>1 nom</sub> dV <sub>SB tot</sub> Total Regulation         V <sub>1 min</sub> to V <sub>1 max</sub> , 0 to 100% I <sub>SB nom</sub> , T <sub>a min</sub> to T <sub>a max</sub> -1.5         +1.5         %V <sub>SB nom</sub> P <sub>SB nom</sub> Nominal Output Power         V <sub>SB</sub> = 3.3 VDC, normal airflow         10         W           IsB nom         Nominal Output Current         V <sub>SB</sub> = 3.3 VDC, normal airflow         3         A <sub>DC</sub> V <sub>SB pp</sub> Output Ripple Voltage         V <sub>SB nom</sub> , I <sub>SB nom</sub> , 20 MHz BW (See Section 5.1)         45         mVpp           dV <sub>SB</sub> Droop         0 - 100% I <sub>SB nom</sub> , I <sub>SB nom</sub>	UIshare		when Bus load < 27 A			5.6	Α
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$dV_{dyn} \\$	Dynamic Load Regulation	•	-0.6		0.6	V
	T <sub>rec</sub>	Recovery Time	$dI_1/dt = 1A/\mu s$ , recovery within 1% of $V_{1 \text{ nom}}$		0.5	1	ms
CLoad         Capacitive Loading         Ta = 25 °C         11000         μF           Standby Output VsB           VSB nom         Nominal Output Voltage         0.5 ·lsB nom, Tamb = 25 °C         3.3         VDC           VSB set         Output Setpoint Accuracy         -1         +1         %V1nom           dVsB tot         Total Regulation         V1 min to V1 max, 0 to 100% IsB nom, Ta min to Ta max         -1.5         +1.5         %V5Bnom           PSB nom         Nominal Output Power         V2 m 3.3 VDC, normal airflow         10         W           IsB nom         Nominal Output Current         V2 m 3.3 VDC, normal airflow         3         ADC           VSB pp         Output Ripple Voltage         V2 m 2.3 VDC, normal airflow         3         45         mVpp           dVsB         Droop         0 - 100% IsB nom, 20 MHz BW (See Section 5.1)         45         mVpp           dVsB         Dynamic Load Regulation         ΔIsB = 50% IsB nom, IsB = 5 100% IsB nom, 15B	t <sub>AC V1</sub>	Start-up Time from AC				2	s
Standby Output VsB           VSB nom         Nominal Output Voltage         0.5 ⋅ lsB nom, Tamb = 25 °C         3.3         VDC           VSB set         Output Setpoint Accuracy         -1         +1         %V1nom           dVsB tot         Total Regulation         V₁ min to V₁ max, 0 to 100% lsB nom, Ta min to Ta max         -1.5         +1.5         %VsBnom           PSB nom         Nominal Output Power         V₂B = 3.3 VDC, normal airflow         10         W           lsB nom         Nominal Output Current         V₃B = 3.3 VDC, normal airflow         3         ADC           V₂B pp         Output Ripple Voltage         V₃B nom, lsB nom, 20 MHz BW (See Section 5.1)         45         mVpp           dV₃B         Droop         0 - 100% lsB nom         67         mV           dV₃B dV₃Bdyn         Dynamic Load Regulation         ΔlsB = 50% lsB nom, lsB = 5 100% lsB nom, clb lsB nom, dlb lsB nom, dlb lsB nom, dlb ld = 0.5 A/μs, recovery within 1% of V₁ nom         -3         3         %VsBnom           Trec         Recovery Time         dlb/dt = 0.5 A/μs, recovery within 1% of V₁ nom         250         μs           tac vsB ise Time         VsB = 1090% VsB nom         4         20         ms	t <sub>V1 rise</sub>	Rise Time	$V_1 = 1090\% \ V_{1 \ nom}$		3		ms
VSB nom         Nominal Output Voltage         0.5 · IsB nom, Tamb = 25 °C         3.3         VDC           VSB set         Output Setpoint Accuracy         -1         +1         %V1nom           dVsB tot         Total Regulation         Vi min to Vi max, 0 to 100% IsB nom, Ta min to Ta max         -1.5         +1.5         %VsBnom           PsB nom         Nominal Output Power         VsB = 3.3 VDC, normal airflow         10         W           IsB nom         Nominal Output Current         VsB = 3.3 VDC, normal airflow         3         ADC           VsB pp         Output Ripple Voltage         VsB nom, IsB nom, 20 MHz BW (See Section 5.1)         45         mVpp           dVsB         Droop         0 - 100% IsB nom, IsB nom, IsB = 5 100% IsB nom, 1sB	$C_{\text{Load}}$	Capacitive Loading	T <sub>a</sub> = 25 °C			11000	μF
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Standby	Output V <sub>SB</sub>					
$V_{SB \ set}  \text{Output Setpoint Accuracy} \qquad \qquad$	$V_{\text{SB nom}}$	Nominal Output Voltage	0.5 dep T = 25 °C		3.3		VDC
PSB nomNominal Output PowerVSB = 3.3 VDC, normal airflow10W $I_{SB nom}$ Nominal Output CurrentVSB = 3.3 VDC, normal airflow3ADCVSB ppOutput Ripple VoltageVSB nom, ISB nom, 20 MHz BW (See Section 5.1)45mVppdVSBDroop0 - 100% ISB nom67mVdVSBdynDynamic Load Regulation Trec $\Delta I_{SB} = 50\%$ ISB nom, ISB = 5 100% ISB nom, dIo/dt = 0.5 A/µs, recovery within 1% of V1 nom-33%VSBnomtAC vSBStart-up Time from AC3stvSB riseRise TimeVSB = 1090% VSB nom420ms	$V_{\text{SB set}}$	Output Setpoint Accuracy	0.5 ISB noni, Tamb – 25 O	-1		+1	$%V_{1nom}$
IsB nomNominal Output Current $V_{SB} = 3.3 \text{ VDC}$ , normal airflow3ADC $V_{SB,pp}$ Output Ripple Voltage $V_{SB,nom}$ , $I_{SB,nom}$ , 20 MHz BW (See Section 5.1)45mVpp $dV_{SB}$ Droop $0 - 100\%$ $I_{SB,nom}$ 67mV $dV_{SB,dyn}$ Dynamic Load Regulation $T_{rec}$ $\Delta I_{SB} = 50\%$ $I_{SB,nom}$ , $I_{SB} = 5 \dots 100\%$ $I_{SB,nom}$ , $I_{SB,nom}$ , $I_{SB,nom}$ $-3$ 3%VsBnom $T_{rec}$ Recovery Time $dI_{O}/dt = 0.5 \text{ A}/\mu\text{s}$ , recovery within 1% of $V_{1,nom}$ 250 $\mu\text{s}$ $I_{AC,VSB}$ Start-up Time from AC3s $I_{VSB,rise}$ Rise Time $V_{SB} = 1090\%$ $V_{SB,nom}$ 420ms	$dV_{SBtot}$	Total Regulation	$V_{imin}toV_{imax},0to100\%I_{SBnom},T_{amin}toT_{amax}$	-1.5		+1.5	$%V_{SBnom}$
$V_{SB pp}  \text{Output Ripple Voltage}  V_{SB nom, I_{SB nom, 20 MHz BW (See Section 5.1)} \qquad \qquad 45  \text{mVpp}$ $dV_{SB}  \text{Droop} \qquad 0 - 100\%  I_{SB nom} \qquad \qquad 67 \qquad \qquad \text{mV}$ $dV_{SBdyn}  \text{Dynamic Load Regulation}  \Delta I_{SB} = 50\%  I_{SB nom, I_{SB}} = 5 \dots 100\%  I_{SB nom, 0} \qquad -3 \qquad \qquad 3 \qquad \%V_{SB nom}$ $T_{rec}  \text{Recovery Time} \qquad \qquad dI_{O}/dt = 0.5  \text{A}/\mu \text{s, recovery within 1\% of V}_{1 nom} \qquad \qquad 250 \qquad \mu \text{s}$ $t_{AC VSB}  \text{Start-up Time from AC} \qquad \qquad 3 \qquad \text{s}$ $t_{VSB rise}  \text{Rise Time} \qquad V_{SB} = 1090\%  V_{SB nom} \qquad \qquad 4 \qquad 20 \qquad \text{ms}$	$P_{\text{SB nom}}$	Nominal Output Power	$V_{\text{SB}} = 3.3 \text{ VDC}$ , normal airflow		10		W
dVsBDroop $0-100\%$ IsB nom $67$ mVdVsBdynDynamic Load Regulation $\Delta$ IsB = $50\%$ IsB nom, IsB = $5100\%$ IsB nom, I	I <sub>SB nom</sub>	Nominal Output Current	$V_{SB} = 3.3 \text{ VDC}$ , normal airflow		3		A <sub>DC</sub>
dVsBdyn Dynamic Load Regulation $\Delta l_{SB} = 50\%$ $l_{SB nom}$ , $l_{SB} = 5 \dots 100\%$ $l_{SB nom}$ , $l$	$V_{\text{SB pp}}$	Output Ripple Voltage	$V_{\text{SB nom}},I_{\text{SB nom}},20~\text{MHz}$ BW (See Section 5.1)			45	mVpp
Trec Recovery Time $\frac{1}{3}$ $\frac{1}{$	dV <sub>SB</sub>	Droop	0 - 100% I <sub>SB nom</sub>		67		mV
t <sub>AC VSB</sub> Start-up Time from AC         3         s           t <sub>VSB rise</sub> Rise Time         V <sub>SB</sub> = 1090% V <sub>SB nom</sub> 4         20         ms	$dV_{\text{SBdyn}}$	Dynamic Load Regulation	$\Delta I_{SB} = 50\%$ $I_{SB nom}$ , $I_{SB} = 5 \dots 100\%$ $I_{SB nom}$ ,	-3		3	$%V_{SBnom}$
tvsB rise Rise Time $V_{SB} = 1090\% V_{SB nom}$ 4 20 ms	T <sub>rec</sub>	Recovery Time	$dI_o/dt = 0.5 \text{ A/}\mu\text{s}$ , recovery within 1% of $V_{1 \text{ nom}}$			250	μS
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	t <sub>AC VSB</sub>	Start-up Time from AC				3	s
$C_{Load}$ Capacitive Loading $T_{amb} = 25  ^{\circ}C$ 1000 $\mu F$	tvsB rise	Rise Time	$V_{SB} = 1090\% \ V_{SB \ nom}$		4	20	ms
	C <sub>Load</sub>	Capacitive Loading	T <sub>amb</sub> = 25 °C			1000	μF



## 5. PROTECTION

General Condition:  $T_A = 0...60$  °C, unless otherwise noted.

PARAMETER		DESCRIPTION / CONDITION	MIN	NOM	MAX	UNIT
F	Input Fuses (L+N)	Not user accessible, quick-acting (F)		16		Α
$V_{1\ OV}$	OV Threshold V <sub>1</sub>		13.5		14.5	VDC
tov v1	OV Latch Off Time V <sub>1</sub>				1	ms
$V_{\text{SB OV}}$	OV Threshold V <sub>SB</sub>		3.6		4.3	VDC
tov vsB	OV Latch Off Time V <sub>SB</sub>				1	ms
I <sub>V1 lim</sub>	Current Limit V <sub>1</sub>	See Figure 5 & Figure 6	112	115	117	$A_{DC}$
I <sub>sb lim</sub>	Current Limit V <sub>1</sub> T <sub>amb</sub> = 25 °C	Standby output can recover.			4.5	Α
I <sub>V1</sub> sc	Max Short Circuit Current V <sub>1</sub>			150		Α
tv1 sc	Short Circuit Regulation Time	$V_1 < 3\ V,$ time until $I_{V1}$ is limited to $< I_{V1\ sc}$		2		ms
$t_{V1\;SC\;off}$	Short Circuit Latch Off Time	Time to latch off when in short circuit		500		ms
T <sub>SD</sub>	Over Temperature on Heat Sinks	Automatic shut-down		115		°C

**NOTE**: The OCP should be derating as below curve if operation temperature increases from 45°C to 60°C, And OCP warning is before 2 A than OCP set point.

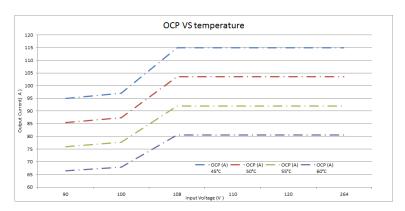


Figure 5. Vin vs Output Current for PET1300-12-054NA

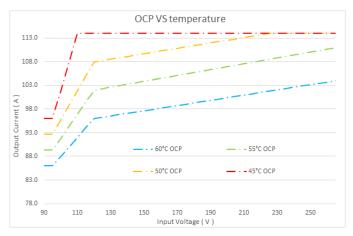


Figure 6. Vin vs Output Current for PET1300-12-054RA



## 6. SIGNALING AND CONTROL

### 6.1 FRONT LEDs

The front-end has 2 front LEDs showing the status of the supply. LED number one is green which indicates presence of AC power, LED number two is bi-colored: green and yellow, which indicates DC power presence or fault. For the position and states of the LEDs see *Table 2*.

POWER SUPPLY CONDITION	GREEN (OK) LED STATUS	AMBER (FAIL) LED STATUS
No AC power to all power supplies	OFF	OFF
Power Supply Failure (includes over voltage, over current, over temperature and fan failure)	OFF	ON
Power Supply Warning events where the power supply continues to operate (high temperature, high power and slow fan)	OFF	1 Hz Blinking
AC Present / 3.3 V <sub>SB</sub> on (PSU OFF)	1 Hz Blinking	OFF
Power Supply ON and OK	ON	OFF

Table 1. LED Status

**NOTE:** When unit see fan failure, unit will shut down and can only be restarted by using PSON\_L signal or AC input power recycling or PMBus® commands. Refer to software specification for detail.

### **6.2 ELECTRICAL CHARACTERISTICS**

General Condition:  $T_A = 0...60$  °C, unless otherwise noted.

PARAMETER	DESCRIPTION / CONDITION		MIN	NOM	MAX	UNIT
PSKILL_H/PSC	DN_L/PRESENT_L					
VIL	Input Low Level Voltage		0		0.8	V
VIH	Input High Level Voltage		2.0		3.6	V
I <sub>IL, H</sub>	Maximum Input Sink or Source Current		0		1	mA
R <sub>puSKILL_H</sub>	Internal Pull Up Resistor on PSKILL_H			10		kΩ
R <sub>puPSON_L</sub>	Internal Pull Up Resistor on PSON_L	nternal Pull Up Resistor on PSON_L				kΩ
R <sub>puPRESENT_L</sub>	Internal Pull Up Resistor on PRESENT_L			None		kΩ
R <sub>LOW</sub>	Resistance Pin to SGND for Low Level		0		1	kΩ
RHIGH	Resistance Pin to SGND for High Level		50			kΩ
PWOK_H Outp	ut					
V <sub>ext</sub>	Maximum External Pull Up Voltage				3.6	V
VoL	Output Low Level Voltage	$I_{\text{sink}} < 2 \text{ mA}$	0		0.4	V
V <sub>OH</sub>	Output High Level Voltage	Isource < 0.5 mA	2.4		3.6	V
R <sub>puPWOK_H</sub>	Internal Pull Up Resistor on PWOK_H			None		kΩ
ACOK_H Outpo	ut					
V <sub>ext</sub>	Maximum External Pull Up Voltage				3.6	V
V <sub>OL</sub>	Output Low Level Voltage	$I_{sink}$ < 2 mA	0		0.4	V
V <sub>OH</sub>	Output High Level Voltage	Isource < 0.5 mA	2.4		3.6	V
R <sub>puACOK_H</sub>	Internal Pull Up Resistor on ACOK_H			None		kΩ
SMB_ALERT_L	. Output					
V <sub>ext</sub>	Maximum External Pull Up Voltage				12	V
VoL	Output Low Level Voltage	Isink < 2 mA	0		0.4	V
Іон	Maximum High Level Leakage Current				10	μΑ
R <sub>puSMB_ALERT_L</sub>	Internal Pull Up Resistor on SMB_ALERT_L			None		kΩ



Asia-Pacific

Europe, Middle East

**North America** 

+86 755 298 85888

+353 61 49 8941

#### **6.3 GRAPHICAL USER INTERFACE**

Bel Power Solutions provide with its "Bel Power Solutions I<sup>2</sup>C Utility" a Windows® XP/Vista/Win7 compatible graphical user interface allowing the programming and monitoring of the PET1300-12-054xA Front-End.

The utility can be downloaded on belfuse.com/power-solutions and supports both the PSMI and PMBus® protocols.

The GUI allows automatic discovery of the units connected to the communication bus and will show them in the navigation tree. In the monitoring view the power supply can be controlled and monitored.

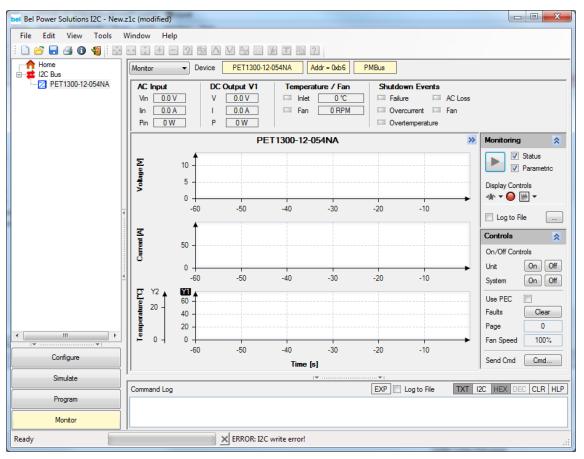


Figure 7. I2C Bus to DSP and EEPROM

COMMAND	10% ~ 20% FULL LOAD	20% ~ 100% FULL LOAD	REMARK
Read_lin	< 0.5 A	+/- 3%	It is for corresponding to max input current
Read_lout	+/- 2%	+/- 2%	It is for corresponding to max output current
Read_Vin	+/- 3%	+/- 2.5 V	
Read_Vout	+/- 2%	+/- 2%	
Read_Pin		+/- 15%	It is for corresponding to max input power
Read_Pout	+/- 3%	+/- 3%	It is for corresponding to max output power

Table 2. Accuracy for PMBus®



#### 6.4 PRESENT L

The PRESENT\_L is an output signal and it is used to sense the number of power supplies in the system (operational or not). This signal is connected to the power supply's output ground. Electrical characteristics see 6.2.

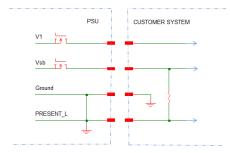


Figure 8. Interconnect Diagram of PRESENT\_L Signal

# 6.5 SMB\_ALERT\_L

The SMB\_ALERT\_L is an output signal and shall be an open collector with the pull-up resistor located at the receiving end and shall capable of sinking up to 4 mA.

This signal indicates that the power supply is experiencing a problem that the user should investigate. This may be asserted due to Critical events or Warning events. See PMBus® specification for further details.

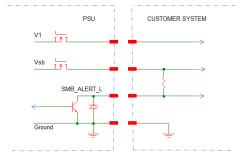


Figure 9. Interconnect Diagram of SMB\_ALERT\_L Signal

## 6.6 PSKILL\_H

This is an input signal and is used to force the 12 V main output off if the supply is removed from the system. At the system level this pin will be connected to the output return directly. When this input is low the power supply will operate. If the input is floating the 12 V main output will turn off while the 3.3 VSB will remain on. This signal overrides all other on-and-off signals. On the power supply connector, this pin is shorter than the others so it is a last-make and first-break contact. See below *Table 3* for Logic Table.

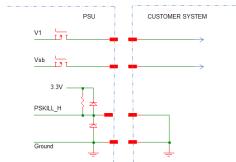


Figure 10. Interconnect Diagram of PSKILL\_H Signal



Asia-Pacific

Europe, Middle East

North America

+86 755 298 85888

+353 61 49 8941

SIGNAL CHARACTERISTICS				
Signal Type: Input Signal to the power supply		Accepts a ground input from the system. Pull-up to 3.3 VSB located in the power supply.		
PS_KILL = Low, PS_ON = Low	ON			
PS_KILL = Open, PS_ON = Low or Open	OFF			
PS_KILL = Low, PS_ON = Open	OFF			
	MIN	MAX		
Source current, Vps_kill =Low		4 mA		

Table 3. PS\_ON\_L Signal Characteristics

## 6.7 PSON\_L

The PS\_ON\_L signal is an input signal used to remotely turn on/off the power supply. PS\_ON\_L is an active LOW signal that turns on the 12 V main output. In the low state this input will not source more than 4 mA of current. The 12 V output will be disabled when this input is driven HIGH, or open circuited. See *Table 4* for Logic Table.

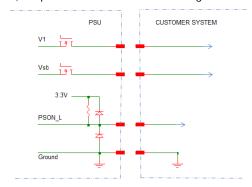


Figure 11. Interconnect Diagram of PSON\_L Signal

SIGNAL CHARACTERISTICS				
Signal Type: Input signal to the power supply	•	Accepts an open collector/drain input from the system. Pull-up to 3.3 VSB located in power supply.		
PS_ON_L = Low, PS_KILL = Low	ON			
PS_ON_L = Open, PS_KILL = Low or Open	OFF			
PS_ON_L = Low, PS_KILL = Open	OFF			
	MIN	MAX		
Output Source Current, VPS_ON_L= Low		4 mA		

Table 4. PS\_ON\_L Signal Characteristics

# 6.8 PW\_OK

PW\_OK is an output signal and will be pulled HIGH by the power supply to indicate that all the outputs are within the regulation limits of the power supply. When 12 V main output is < 10.9 V or > 13.2 V, or if any of the outputs fail due to over current protection, over voltage protection, over temperature, or fan failure then this output will be driven LOW. In the event when AC mains power is lost, this signal will be driven LOW at least 20 ms before the +3.3 VSB output is lost. The output will be an open collector/drain. The start of the PW\_OK delay time shall be inhibited as long as any power supply's 12 V output is in current limit. See *Table 5*.



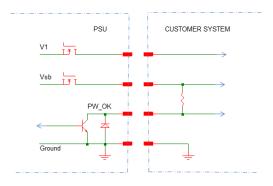


Figure 12. Interconnect Diagram of PW\_OK Signal

SIGNAL CHARACTERISTICS				
Signal Type: Output signal from the power supply		Open collector/drain (system side to provide pull-up, another pull-up to 3.3 VSB could also be located in the power supply)		
PW_OK = High	Power OK			
PW_OK = Low	Power Not OK			
	MIN	MAX		
Input Sink current, PW_OK = Low		4 mA		
Output Source current, PW_OK = High		2 mA		

Table 5. PW\_OK Signal Characteristics

## 6.9 AC\_OK

This signal is an output signal and will be asserted, driven HIGH, by the power supply to indicate that the input voltage meets the minimum requirements of Section 3.1.3. After falling outside the input voltage requirements for more than 20 ms, the signal must be driven LOW. The output will be an open collector/drain. See below *Table 6*.

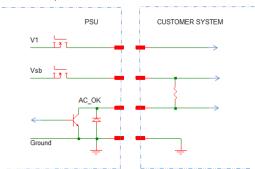


Figure 13. Interconnect Diagram of AC\_OK Signal

SIGNAL CHARACTERISTICS				
Signal Type: Output signal from the power supply		Open collector/drain (system side to provide pull-up, another pull-up to 3.3 VSB could also be located in the power supply)		
AC_OK = High	AC OK	AC OK		
AC_OK = Low	AC Low (Not OK)	AC Low (Not OK)		
	MIN	MAX		
Input Sink current, AC_OK = Low		4 mA		
Output Source current, AC_OK = High		2 mA		

Table 6. AC\_OK Signal Characteristics



Asia-Pacific

Europe, Middle East

**North America** 

+86 755 298 85888

+353 61 49 8941

### 6.10 CURRENT SHARING

All outputs shall be capable of operating in a redundant current share mode. A maximum of 6 power supplies may be operated in parallel. All outputs shall incorporate an isolation device (Or-ing MOSFET or diode) for fault isolation. Filter capacitors that are located after the isolation device shall be of high reliability and shall be de-rated sufficiently to minimize failures.

The 3.3 V output current sharing shall be of a droop type. The +12 V current sharing shall be a single wire type, active current sharing. Connecting the Ishare (current share) pins of each power supply together shall enable the current share feature. Shorting or opening of a current share pin shall not cause the output voltage to go out of steady state regulation.

For 12 V output the Ishare (load sharing) voltage shall be a linear function Ishare  $[V] = 8 \times 10ut/108$  (with 8 V at 108 A) for a single power supply (~74 mV/A).

At light load, the load share becomes difficult because of low feedback signal. Refer to Table 2 for current sharing accuracy. The current balance accuracy is calculated as: 2\*|I1-I2|/ (I1+I2), where the I1 is the PSU1 load current and I2 is the PSU2 load current.

#### 6.11 REMOTE SENSE

The outputs specified shall incorporate remote sense and will compensate for specified load cable drop. In the event of loss of remote sense, all outputs shall revert to internal sense so as to limit the outputs to less than 105% of nominal.



## 7. TIMING DIAGRAM AND TABLE

Unless defined otherwise, all control signals shall be TTL compatible with respect to the output return and shall be isolated from the primary circuit and be SELV rated. All input signals shall be driven from an open collector with the pull-up resistor located in the power supply and shall be capable of sourcing up to 4 mA. General LVTTL signal levels are specified in below table except where explicitly specified otherwise.

PARAMETER	SYMBOL	MIN	MAX	UNITS
Output High Voltage	Voh	2.4	3.6	V
Output Low Voltage	Vol	0	0.4	V
Input High Voltage	Vih	2.0	3.6	V
Input Low Voltage	Vil	0	0.8	V

Table 7. Low-Voltage TTL (LVTTL) Voltage Levels

Figure 14. Timing Diagram

PARAMETER	CONDITION / COMMENTS	MIN	TYP	MAX	UNITS
T1 (Tout_rise)	Output voltage rise time from each main output	0.5		100	ms
T2 (Tsb_on_delay)	Delay from AC being applied to 3V3 being within regulation			2500	Ms
T3 (Tac_on_delay)	Delay from AC being applied to all output voltages being within regulation			3000	ms
T4 (Tvout_holdup)	Time all output voltages, including 3V3, stay within regulation after loss of AC	10			ms
T5 (Tpw_ok_holdup)	Delay from loss of AC to de-assertion of PW_OK	5			ms
T6 (Tps_on_delay)	Delay from PS_ON_L active to output voltages within regulation limits	5		400	ms
T7 (Tps_on_pw_ok)	Delay from PS_ON_L de-active to PW_OK being de-asserted			50	ms
T8 (Tac_ok_off)	Delay from loss of AC input to de-assertion of AC_OK			20	ms
T9 (Tpw_ok_on)	Delay from output voltages within regulation limits to PW_OK asserted at turn on	100		1000	ms
T10 (Tpw_ok_off_12V)	Delay from PW_OK de-asserted to 12 VDC dropping out of regulation limits	1		700	ms
T11 (Tpw_ok_off_3V3)	Delay from PW_OK de-asserted to 3V3 dropping out of regulation limits	20			ms
T12 (Tsb_vout)	Delay from 3V3 being in regulation to 12 VDC being in regulation at AC turn on.	50		1000	ms
T13 (Tac_ok_on)	Delay from AC being applied to assertion of AC_OK			1500	ms



Asia-Pacific

Europe, Middle East

North America

+86 755 298 85888

+353 61 49 8941

## 8. ELECTROMAGNETIC COMPATIBILITY

## **8.1 IMMUNITY**

PARAMETER	DESCRIPTION / CONDITION	CRITERION
ESD Contact Discharge	IEC / EN 61000-4-2, ±8 kV, 25+25 discharges per test point (metallic case, LEDs, connector body)	А
ESD Air Discharge	IEC / EN 61000-4-2, ±15 kV, 25+25 discharges per test point (non-metallic user accessible surfaces)	А
Radiated Electromagnetic Field	IEC / EN 61000-4-3, 10 V/m, 1 kHz/80% Amplitude Modulation, 1 μs Pulse Modulation, 10 kHz2 GHz	А
Burst	IEC / EN 61000-4-4, level 3 AC port ±2 kV, 1 minute DC port ±1 kV, 1 minute	А
Surge	IEC / EN 61000-4-5 4 kV CM 2 kV DM	А
RF Conducted Immunity	IEC/EN 61000-4-6, Level 3, 10 Vrms, CW, 0.1 80 MHz	Α
Voltage Dips and Interruptions	IEC/EN 61000-4-11 1: Vi 230 V, 100% Load, Phase 0 °, Dip 100%, Duration 10 mS 2: Vi 230 V, 100% Load, Phase 0 °, Dip 100%, Duration 20 mS 3: Vi 230 V, 100% Load, Phase 0 °, Dip 100%, Duration > 20 mS	A V <sub>SB</sub> : A, V <sub>1</sub> : B V <sub>SB</sub> , V <sub>1</sub> : B

**NOTE:** Most of the immunity requirements are derived from EN 55024: 1998/A2:2003.

### **8.2 EMISSION**

PARAMETER	DESCRIPTION / CONDITION	CRITERION
Conducted Emission	EN55022 / CISPR 22: 0.15 30 MHz, QP and AVG, single unit	Class A
Conducted Emission	EN55022 / CISPR 22: 0.15 30 MHz, QP and AVG, 2 units in rack system	Class A
Radiated Emission	EN55022 / CISPR 22: 30 MHz 1 GHz, QP, single unit	Class A
Hadiated Emission	EN55022 / CISPR 22: 30 MHz 1 GHz, QP, 2 units in rack system	Class A
Harmonic Emissions	IEC61000-3-2, Vin = 115 VAC / 60 Hz, & Vin = 230 VAC/ 50 Hz, 100% Load	Class A
Acoustical Noise	46 dBA at 1 meter, 25 °C, 50% Load	-
AC Flicker	IEC61000-3-3, Vin = 230 VAC / 60 Hz, 100% Load	Pass

# 9. SAFETY / AGENCY APPROVALS

Maximum electric strength testing is performed according to UL / CSA 62368-1, IEC/EN 62368-1. Input-to-output electric strength tests should not be repeated in the field. Bel Power Solutions will not honor any warranty claims resulting from electric strength field tests.

PARAMETER	DESCRIPTION / CONDITION	MIN NOM	MAX	UNIT	
Agency Approvals	Approved to the latest edition of the following standards: UL / CSA 62368-1 IEC / EN 62368-1	dy ion)			
	Input (L/N) to case (PE)	Basic			
Isolation Strength	Input (L/N) to output	Reinforced			
	Output to case (PE)	Functional			
Electrical Strength Test	Input to case	2500		VDC	
	Input to output	4000		VDC	



## 10. ENVIRONMENTAL

PARA	AMETER	DESCRIPTION / CONDITION	MIN NOM	MAX	UNIT
TA	Ambient Temperature	$V_{imin}$ to $V_{imax},\;I_{1norm},\;I_{SBnom}$	0	+60	°C
Ts	Storage Temperature	Non-operational	-40	+85	°C
	Altitude	Operational, above Sea Level	-	10,000	Feet
Na	Audible Noise	$V_i = 230 \text{ VAC}, 50\% \text{ I}_{o \text{ nom}}, T_A = 25^{\circ}\text{C}$	46		dBA

**NOTE:** Refer to Figure 2 & 3 for Derating.

## 11. MECHANICAL

PAR	AMETER	DESCRIPTION / CONDITION	MIN	NOM	MAX	UNIT
		Width	54.1	54.5	54.9	
	Dimensions	Height	39.6	40.0	40.4	mm
		Depth	321.1	321.6	322.1	
М	Weight			1.09		kg

A 3D step file of the power supply casing is available on request.

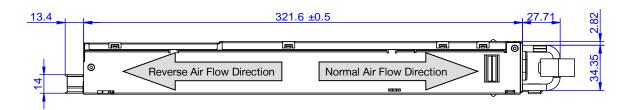


Figure 15. Side View 1

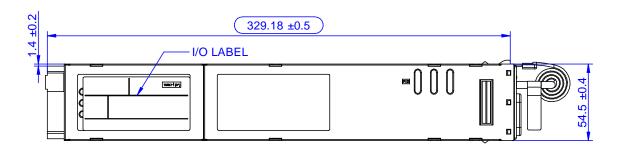


Figure 16. Top View



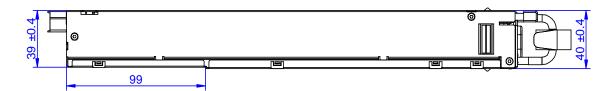


Figure 17. Side View 2

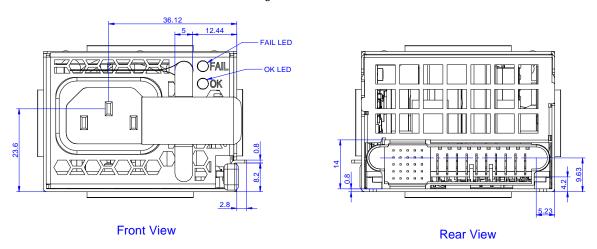
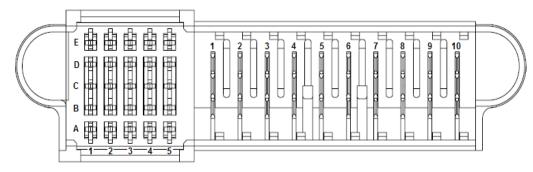


Figure 18. Front and Rear View



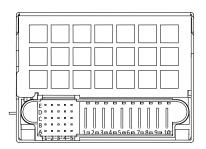
# 12. CONNECTIONS



Unit: Tyco Electronics P/N 1926736-2 or FCI 10135322-002LF or equivalent

Counter part: Tyco Electronics P/N 2-1926739-5 or FCI 10108888-R10253SLF (Bel Power Solutions P/N: ZES.00672)

PIN	NAME	DESCRIPTION
Output		
6, 7, 8, 9, 10	V1	+12 VDC main output
1, 2, 3, 4, 5	PGND	Power ground (return)
Control Pins		
A1, B1, C1, D1, E1	VSB	Standby positive output (+3.3 V)
A2, B2	SGND	Signal ground (return)
C2	NC	Reserved
D2	NC	Reserved
E2	NC	Reserved
A3	PS_KILL	Power supply kill (lagging pin)
B3	NC	Reserved
C3	SDA	I <sup>2</sup> C data signal line
D3	V1_SENSE_R	Main output negative sense
E3	V1_SENSE	Main output positive sense
A4	SCL	I <sup>2</sup> C clock signal line
B4	PS_ON_L	Power supply on input (connect to A2/B2 to turn unit on)
C4	ALERT_L	SMB Alert signal output
D4	ISHARE	12 V current share signal (LS)
E4	AC_OK	AC input OK signal
A5	A0	Address 0
B5	NC	Reserved
C5	PW_OK	Power OK signal output (lagging pin)
D5	A1	Address 1
E5	PRESENT_L	Power supply present (lagging pin)





# 13. ACCESSORIES

ITEM	DESCRIPTION	ORDERING PART NUMBER	SOURCE
THE RESERVE OF THE PARTY OF THE	Bel Power Solutions I <sup>2</sup> C Utility Windows XP/Vista/7 compatible GUI to program, control and monitor PET Front-Ends (and other I <sup>2</sup> C units)	N/A	belfuse.com/power-solutions
Evaluation board	Dual Connector Board  Connector board to operate 2 PET units in parallel. Includes an on-board USB to I <sup>2</sup> C converter (use <i>Bel Power Solutions FC Utility</i> as desktop software).	VRA.00333.0	Bel Power Solutions



# 14. PMBus® COMMUNICATION

## **14.1 ADDRESS SELECT**

A2	A1	A0	UNIT ADDRESS	EEPROM ADDRESS
0	0	0	0xB0	0xA0
0	0	1	0xB2	0xA2
0	1	0	0xB4	0xA4
0	1	1	0xB6	0xA6

**NOTE:** A2 = 1 is not implemented.

Table 8. Address Select

## 14.2 PMBus® COMMANDS

### NOTE:

Reference: PMBus® Power System Management Protocol Specification Part II – Command Language Revision 1.1. Commands not included in the table below are <u>Not Implemented</u>. Feature that are To Be Defined (TBD), or <u>Not Implemented</u> are shaded. R = Read-Only; RW = Read/Write; W = Write-Only.

COMMAND NAME BIT NAME	CODE	BIT	VALUE	ACCESS	DATA BYTES	REMARKS
PAGE	00h		-	RW	1	Page 0 applies to + 12 V output Page 1 applies to + 3.3 V output Other Page values are considered invalid and will generate an INVALID_DATA error.
OPERATION	01h				1	
		7-6	-	RW		0b00 = OFF 0b10 = ON (Default)
		5-0	0d	R		Not Implemented
CLEAR_FAULTS	03h		-	W	0	Clear all bits in all status registers.
CAPABILITY	19h			R	1	
PACKET_ERROR_CHECKING		7	0b1			Supported
MAXIMUM_BUS_SPEED		6-5	0b01			400 kHz
SMBALERT#		4	0b1			Supported
RESERVED		3-0	0b0000			Reserved
VOUT_MODE	20h		-	R	1	
MODE		7-5	0b000			Linear
PARAMETER		4-0	0b10111			N = -9
FAN_CONFIG_1_2	3Ah			R	1	
		7	0b1			Fan1 Installed
		6	0b0			Fan1 Commanded in Duty Cycle
		5-4	0b01			Fan1 (2) Tachometer Pulses per Revolution
		3	0b0			Fan2 Not Installed
		2	0b0			Don't Care
		1-0	0b00			Don't Care
FAN_COMMAND_1	3Bh		-	RW	2	MIN = 0 → 0%  MAX = 100 → 100%  Values outside limits will generate INVALID_DATA error.  Write request is executed only if the desired Fan speed is greater than what is required by the PSU.  Fan Speed = FAN_COMMAND*21000RPM/100



Asia-Pacific

Europe, Middle East

**North America** 

+86 755 298 85888

+353 61 49 8941

COMMAND NAME BIT NAME	CODE	BIT	VALUE	ACCESS	DATA BYTES	REMARKS
STATUS_BYTE	78h			R	1	STATUS bits remain set, even if the fault or warning is removed. They are reset by: CLEAR_FAULTS Command AC Recycle PSON Recycle
BUSY		7	0b0			Not Implemented
OFF		6	-			
VOUT_OV		5	-			
IOUT_OC		4	-			
VIN_UV		3	-			
TEMPERATURE		2	-			
CML		1	-			
NONE_OF_THE_ABOVE		0	0b0			Not Implemented
STATUS_WORD	79h			R	2	
VOUT		F	-			
IOUT/POUT		Е	-			
INPUT		D	-			
MFR		С	-			
POWER_GOOD#		В	-			
FANS		Α	-			
OTHER		9	_			
UNKNOWN		8	0b0			Not Implemented
STATUS_BYTE		7-0	-			See STATUS BYTE
STATUS_VOUT	7Ah	, ,		R	1	000 01/1100_2112
VOUT_OV_FAULT	7741	7	-			Asserts when an OV fault condition is detected on V1 output.  SMB Alert Mask = 1 (Default)
VOUT_OV_WARNING		6	0b0			Not Implemented
VOUT_UV_WARNING		5	0b0			Not Implemented
VOUT_UV_FAULT		4	-			Asserts when an UV fault condition is detected on V1 output.  SMB Alert Mask = 1 (Default)
VOUT_MAX_WARNING		3	0b0			Not Implemented
TON_MAX_FAULT		2	-			Asserts when V1 output is not in regulation 3s after PSON and AC is applied.  SMB Alert Mask = 1 (Default)
TOFF_MAX_WARNING		1	0b0			Not Implemented
PWR_ON_TRACKING_ERROR		0	0b0			Not Implemented
STATUS_IOUT	7Bh			R	1	
IOUT_OC_FAULT		7	-			Asserts when an OC fault condition is detected on V1 output.  SMB Alert Mask = 1 (Default)
IOUT_OC_FAULT_LV		6	0b0			Not Implemented
IOUT_OC_WARNING		5	0b0			Asserts when an OC warning condition is detected on V1 output.  SMB Alert Mask = 0 (Default)
IOUT_UC_FAULT		4	0b0			Not Implemented
ISHARE_FAULT		3	0b0			Not Implemented
PIN_LIMITING_MODE		2	0b0			Not Implemented
POUT_OP_FAULT		1	0b0			Not Implemented
POUT_OP_WARNING		0	0b0			Not Implemented
STATUS_INPUT	7Ch			R	1	
VIN_OV_FAULT		7	0b0			Not Implemented
VIN_OV_WARNING		6	0b0			Not Implemented
VIN_UV_WARNING		5	0b0			Not Implemented



COMMAND NAME BIT NAME	CODE	BIT	VALUE	ACCESS	DATA BYTES	REMARKS
VIN_UV_FAULT		4	0b0			Not Implemented
UNIT_OFF_VIN_LOW		3	-			Asserts when the PSU is disabled because of low input voltage.  SMB Alert Mask = 1 (Default)
IIN_OC_FAULT		2	0b0			Not Implemented
IIN_OC_WARNING		1	0b0			Not Implemented
PIN_OP_WARNING		0	0b0			Not Implemented
STATUS_TEMPERATURE	7Dh			R	1	
OT_FAULT		7	-			Asserts when an OT fault condition is detected. SMB Alert Mask = 1 (Default)
OT_WARNING		6	-			Asserts when an OT warning condition is detected. SMB Alert Mask = 1 (Default)
UT_WARNING		5	0b0			Not Implemented
UT_FAULT		4	0b0			Not Implemented
RESERVED		3-0	0b0000			Reserved
STATUS_CML	7Eh			R	1	
INVALID_COMMAND		7	-			Asserts when the System tries to access unsupported commands, write to supported commands with read-only access, or read supported commands with write-only access.  SMB Alert Mask = 0 (Default)  Asserts when the System tries to write invalid data
INVALID_DATA		6	-			(including when PEC byte is incorrect) to supported commands with write access.  SMB Alert Mask = 0 (Default)
PEC_FAIL		5	-			Asserts when the received PEC byte is incorrect. SMB Alert Mask = 0 (Default)
MEMORY_FAULT		4	0b0			Not Implemented
PROCESSOR_FAULT		3	0b0			Not Implemented
RESERVED		2	0b0			Reserved
OTHER_COMM_FAULT		1	0b0			Asserts when the communication between monitoring components inside the PSU is lost. SMB Alert Mask = 0 (Default)
OTHER_MEMORY_FAULT		0	0b0			Not Implemented
STATUS_OTHER	7Fh			R	1	
RESERVED		7	0b0			Reserved
RESERVED		6	0b0			Reserved
INPUT A FUSE		5	0b0			Not Implemented
INPUT B FUSE		4	0b0			Not Implemented
INPUT A ORING		3	0b0			Not Implemented
INPUT B ORING		2	0b0			Not Implemented
OUTPUT ORING		1	-			Asserts when a fault is detected on the V1 ORing device.  SMB Alert Mask = 0 (Default)
RESERVED		0	0b0			Reserved
STATUS_MFR_SPECIFIC	80h			R	1	
RESERVED		7	0b0			Reserved
RESERVED		6	0b0			Reserved
RESERVED		5	0b0			Reserved
RESERVED		4	0b0			Reserved
VSB_UV_FAULT		3	-			Asserts when an UV fault condition is detected on Vsb output.  SMB_Alert Mask = 0 (Default)
VSB_OV_FAULT		2	-			Asserts when an OV fault condition is detected on Vsb output.  SMB_Alert Mask = 0 (Default)



Asia-Pacific

Europe, Middle East

**North America** 

+86 755 298 85888

+353 61 49 8941

COMMAND NAME BIT NAME	CODE	BIT	VALUE	ACCESS	DATA BYTES	REMARKS
PHASE_SHARE_FAULT		1	-			Asserts when there is a current imbalance between DCDC Phases.  SMB_Alert Mask = 0 (Default)
HOLDUP_FAULT		0	-			Asserts when V1 goes out of regulation if Bulk voltage level is reduced.  SMB Alert Mask = 0 (Default)
STATUS_FANS_1_2	81h			R	1	
FAN1_FAULT		7	-			Asserts when a Fan fault condition is detected. SMB Alert Mask = 1 (Default)
FAN2_FAULT		6	0b0			Not Implemented
FAN1_WARNING		5	0b0			Not Implemented
FAN2_WARNING		4	0b0			Not Implemented
FAN1_SPEED_OVERRIDE		3	-			Asserts when the Fan is running according to the speed defined by the System.  SMB Alert Mask = 0 (Default)
FAN2_SPEED_OVERRIDE		2	0b0			Not Implemented
AIR_FLOW_FAULT		1	0b0			Not Implemented
AIR_FLOW_WARNING		0	0b0			Not Implemented
READ_VIN	88h		-	R	2	Linear Format, N = -1
READ_IIN	89h		-	R	2	Linear Format, N = -6
READ_VOUT	8Bh		-	R	2	Linear Format, N = -9 Refer to Section 8.3.1 of PMBus® Spec Part II Revision 1.1
READ_IOUT	8Ch		-	R	2	Linear Format, N = -3
READ_TEMPERATURE_1	8Dh		-	R	2	Linear Format, N = -2 Inlet Temperature
READ_TEMPERATURE_2	8Eh		-	R	2	Linear Format, N = -2 Outlet Temperature
READ_TEMPERATURE_3	8Fh		-	R	2	Linear Format, N = -2 ORing FET Temperature
READ_FAN_SPEED_1	90h		-	R	2	Linear Format, N = 5
READ_POUT	96h		-	R	2	Linear Format, N = 1
READ_PIN	97h		-	R	2	Linear Format, N = 1
MFR_ID	99h		-	R	CNT+9	ID = Bel Power Format: ASCII
MFR_MODEL	9Ah		-	R	CNT+16	MODEL = PET1300-12-054xA Format: ASCII
MFR_REVISION	9Bh		-	R	CNT+3	REVISION = vvv Format: ASCII
MFR_LOCATION	9Ch		-	R	2	LOCATION = xx Format: ASCII
MFR_DATE	9Dh		-	R	CNT+4	DATE = yyww Format: ASCII
MFR_SERIAL	9Eh		-	R	CNT+18	SERIAL = xxzzzzzzzvvvuuuuu Format: ASCII
CALIBRATION_POINTER	C0h		-	RW	2	For Bel Power Solutions Use Only
CALIBRATION_DATA	C1h		-	RW	2	For Bel Power Solutions Use Only
CALIBRATION_COMMAND	C2h		-		2	For Bel Power Solutions Use Only
RESERVED		F-1	0d	R		Reserved
COMMIT_TO_FLASH		0	-	RW		0 = No Action 1 = Commit RAM to Flash
READ_VSTBY	C3h		-	R	2	For Bel Power Solutions Use Only Same format as READ_VOUT
READ_ISTBY	C4h		-	R	2	For Bel Power Solutions Use Only Same format as READ_IOUT
READ_VOUT_INT	C5h		-	R	2	For Bel Power Solutions Use Only Same format as READ_VOUT
BOOTLOADER_STATUS_REQUEST	C7h			RW	2	For Bel Power Solutions Use Only
BOOTLOADER_PAGE_DATA	C8h		-	W	-	For Bel Power Solutions Use Only
PRODUCT_ID_NUMBER	C9h			R	2	For Bel Power Solutions Use Only



COMMAND NAME BIT NAME	CODE	ВІТ	VALUE	ACCESS	DATA BYTES	REMARKS
						Refer to Table 3
FW_REV	CAh			R	2	For Bel Power Solutions Use Only
SEC_DSP_MAJOR		F-C	-			M = 0 to 9
SEC_DSP_MINOR		B-8	-			m = 0 to 9 i.e: Mm = $25 \rightarrow$ Revision 2.5
PRI_DSP_MAJOR		7-4	-			M = 0 to 9
PRI_DSP_MINOR		3-0	-			m = 0 to 9 i.e: Mm = 13 → Revision1.3
SEC_CTRL1	CCh			R		For Bel Power Solutions Use Only
SEC_CTRL2	CDh			R		For Bel Power Solutions Use Only
SEC_STAT	CEh			R		For Bel Power Solutions Use Only
PRI_STAT	CFh			R		For Bel Power Solutions Use Only
MFR_SPECIFIC_00 (PSU_CONTROL)	D0h				2	
RESERVED		F-1	0d	R		Reserved
EEPROM_WP		0	-	RW		EEP Write-Protect (WP) Control 0 = Enable WP (Default) 1 = Disable WP
MFR_SPECIFIC_05 (FW_VERSION)	D5h		-	R	8	Format: xx.xx.xx (e.g. 01.02.01). The length is fixed at 8 Ascii characters. Each field will be an Ascii value stored in one byte.  * For example: aa.bb.cc, where aa is development stage (P0, P1 A0); bb is primary mcu firmware revision (00 ~ 99); cc is secondary mcu firmware revision (00 ~ 99).  NO BYTE COUNT
MFR_SPECIFIC_09 (SMB ALERT MASKING)	D9h		-	RW	7	Refer to Table 4 NO BYTE COUNT

Table 9. PMBus® Commands

# For more information on these products consult: tech.support@psbel.com

NUCLEAR AND MEDICAL APPLICATIONS - Products are not designed or intended for use as critical components in life support systems,

equipment used in hazardous environments, or nuclear control systems. **TECHNICAL REVISIONS** - The appearance of products, including safety agency certifications pictured on labels, may change depending on the date manufactured. Specifications are subject to change without notice.



Asia-Pacific

Europe, Middle East

**North America** 

+86 755 298 85888

+353 61 49 8941